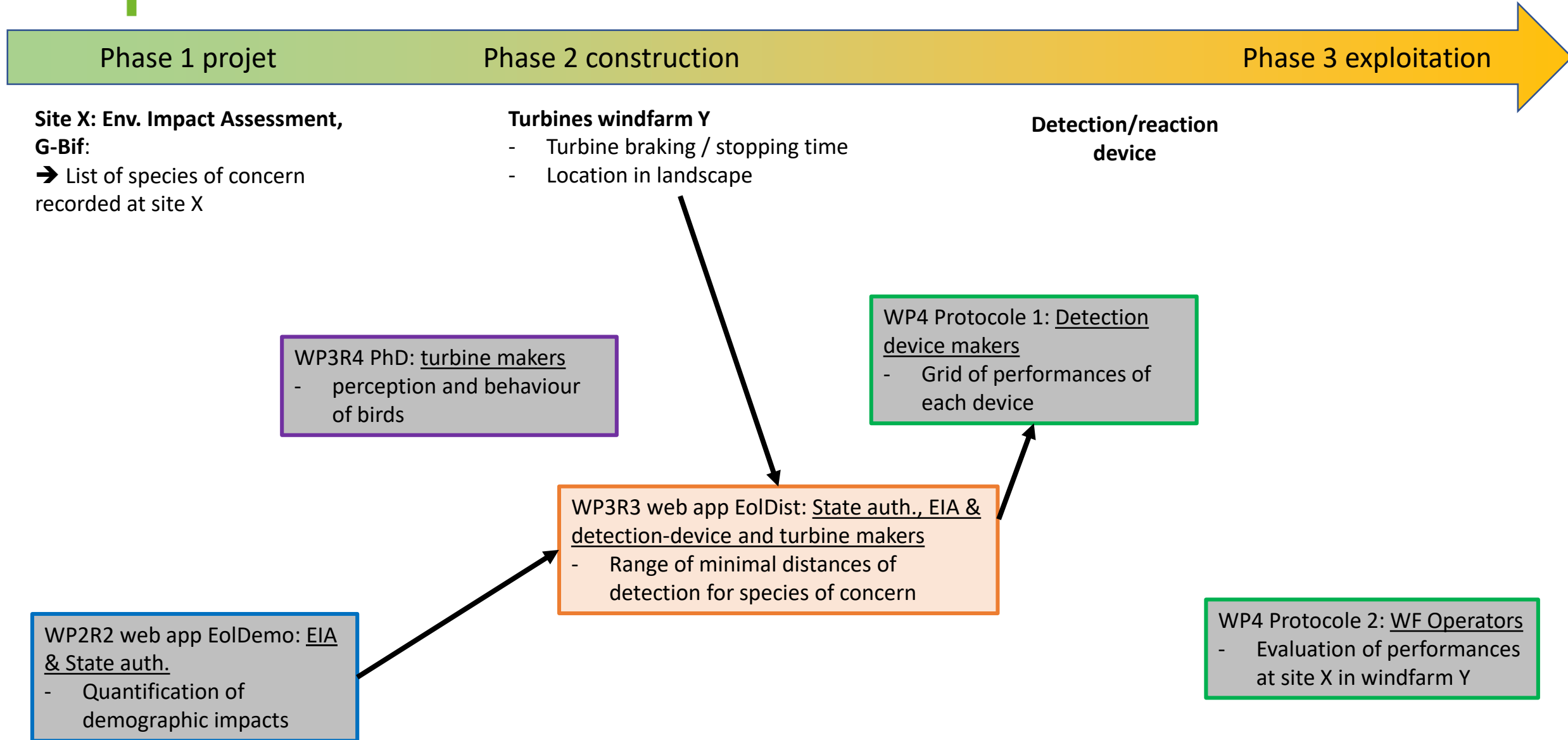


«Reduction of Avian Mortality in Operating Wind Farms»

WP3 R3 : Determine minimum detection distances for birds to avoid collisions

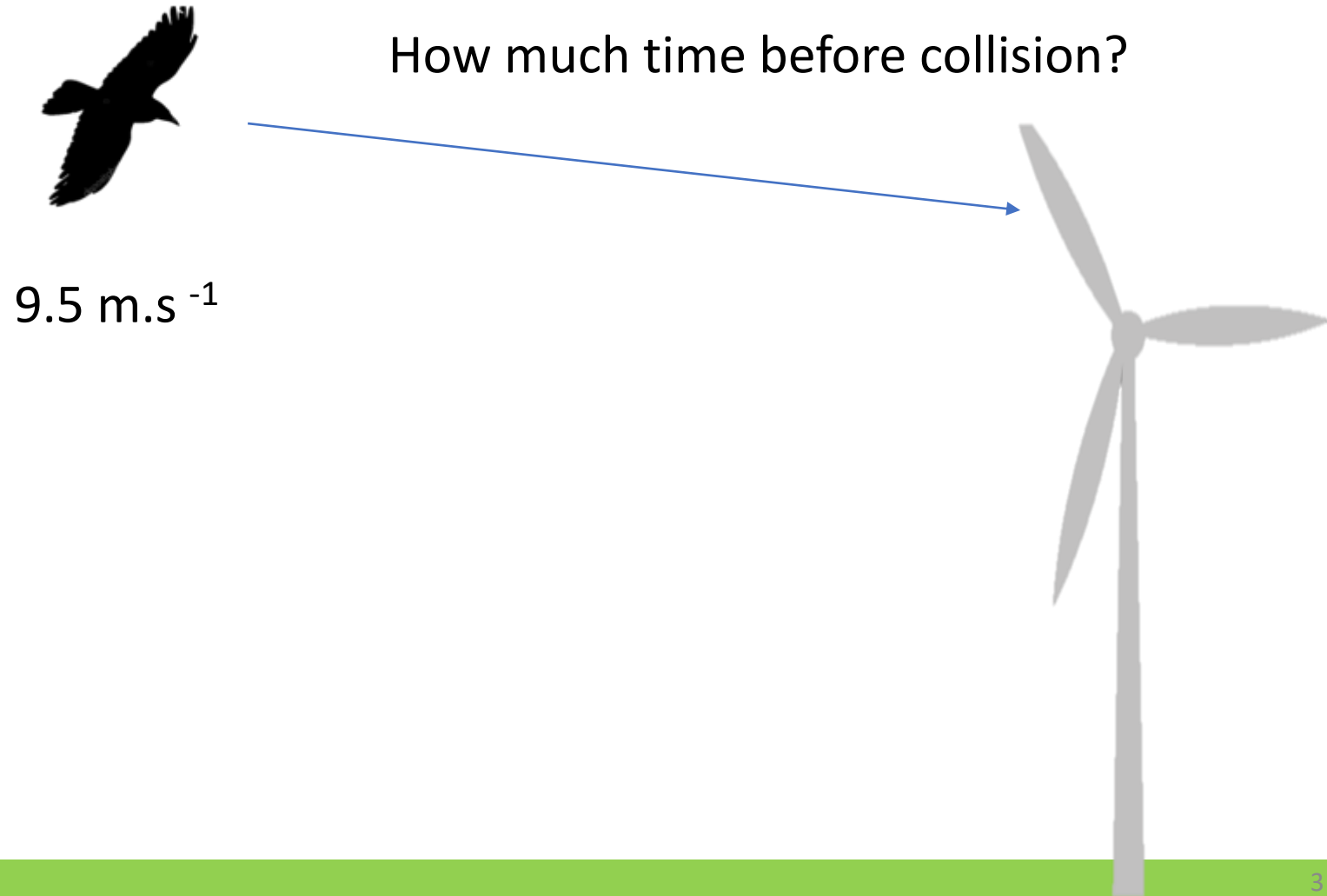
Julie FLUHR, Olivier DURIEZ, Axèle ALEXIS, Aurélien BESNARD

18/11/2021



Underlined = main users / beneficiaries

Why studying minimal detection distance?



Why studying minimal detection distance?



How much time ~~before collision~~
to shutdown turbine?



9.5 m.s⁻¹

$$\text{Speed} = \frac{\text{distance}}{\text{time}}$$



$$\text{time} = \frac{\text{distance}}{\text{speed}}$$

Why studying minimal detection distance?

Time to shutdown = T_{decision}

$$\text{time} = \frac{\text{distance}}{\text{speed}}$$



**Detection + classification
of the target**

**Analysis collision risk~
trajectory, speed, altitude**

**DETECTION / REACTION
device**



Why studying minimal detection distance?

$$\text{Time to shutdown} = T_{\text{decision}} + T_{\text{signal}}$$

$$\text{time} = \frac{\text{distance}}{\text{speed}}$$



Detection + classification
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Analysis collision risk~
trajectory, speed, altitude

Sending command
Detection device => SCADA

Processing command
SCADA => turbine

DETECTION / REACTION
device

Wind Turbine



Why studying minimal detection distance?

$$\text{Time to shutdown} = T_{\text{decision}} + T_{\text{signal}} + T_{\text{rotor}}$$

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Detection + classification
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Slow / Stop rotor ~
turbine model + wind speed

DETECTION / REACTION
device

Wind Turbine

Why studying minimal detection distance?

Time to shutdown = T_{decision} + T_{signal} + T_{rotor}

$$\text{time} = \frac{\text{distance}}{\text{speed}}$$



9.5 m.s⁻¹

How much time to shutdown turbine?

At what distance should we detect the bird to have enough time to shutdown turbine?



Why studying minimal detection distance?

$$\text{Time to shutdown} = T_{\text{decision}} + T_{\text{signal}} + T_{\text{rotor}} \qquad \text{time} = \frac{\text{distance}}{\text{speed}}$$



9.5 m.s⁻¹

How much time to shutdown turbine?

At what distance should we detect the bird to have enough time to shutdown turbine?

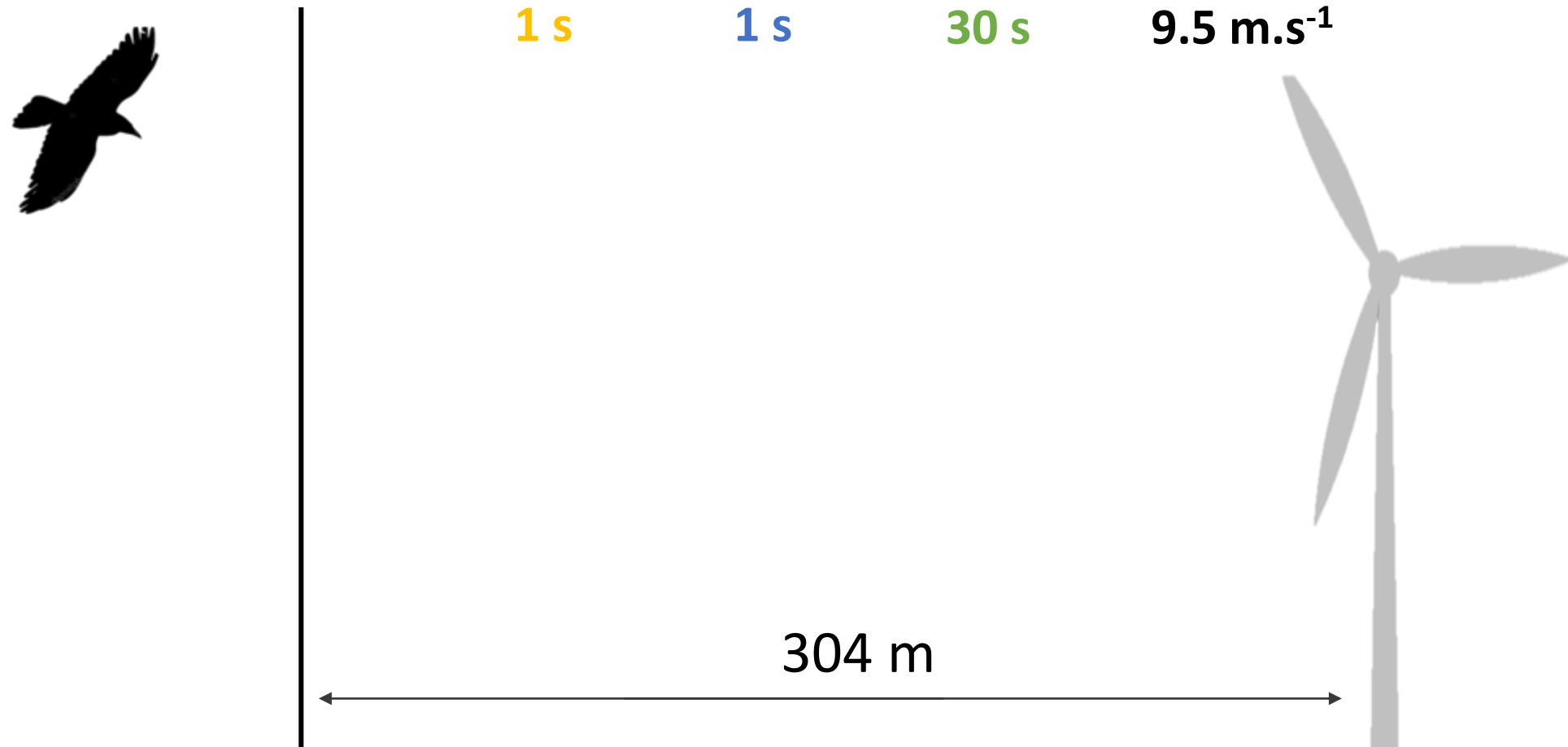


$$\text{Distance} = \text{time} * \text{speed}$$

$$\text{Minimal distance detection} = (T_{\text{decision}} + T_{\text{signal}} + T_{\text{rotor}}) * \text{Flight speed}$$

Why studying minimal detection distance?

Minimal distance detection = $(T_{\text{decision}} + T_{\text{signal}} + T_{\text{rotor}}) * \text{Flight speed}$



Why studying minimal detection distance?

$$\text{Minimal distance detection} = (T_{\text{decision}} + T_{\text{signal}} + T_{\text{rotor}}) * \text{Flight speed}$$



1 s

1 s

30 s

12.5 m.s⁻¹

384 m



Why studying minimal detection distance?

Minimal distance detection = $(T_{\text{decision}} + T_{\text{signal}} + T_{\text{rotor}}) * \text{Flight speed}$



1 s

1 s

20 s

12.5 m.s⁻¹

264 m



Why studying minimal detection distance?

$$\text{Minimal distance detection} = (T_{\text{decision}} + T_{\text{signal}} + T_{\text{rotor}}) * \text{Flight speed}$$



Detection + classification
of the target

Analysis collision risk~
trajectory, speed, altitude

Sending command
Detection device => SCADA

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Wind Turbine

Slow / Stop rotor ~
turbine model + wind speed

DETECTION / REACTION
device



Objective: Web Application EoIDist

2 problems:

1. Need to know duration of shutdown of rotor

- Rarely available

2. Need to build a database of flight speed for many species of concern

- Difficult to measure
- Published values disseminated



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→ Creation of a web application : calculate minimal detection distances for a range of bird species of concern

Users: Environmental Impact Assessment companies, detection-device makers, turbine makers, State authorities



Objective: Web Application EoIDist

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Wind Turbine

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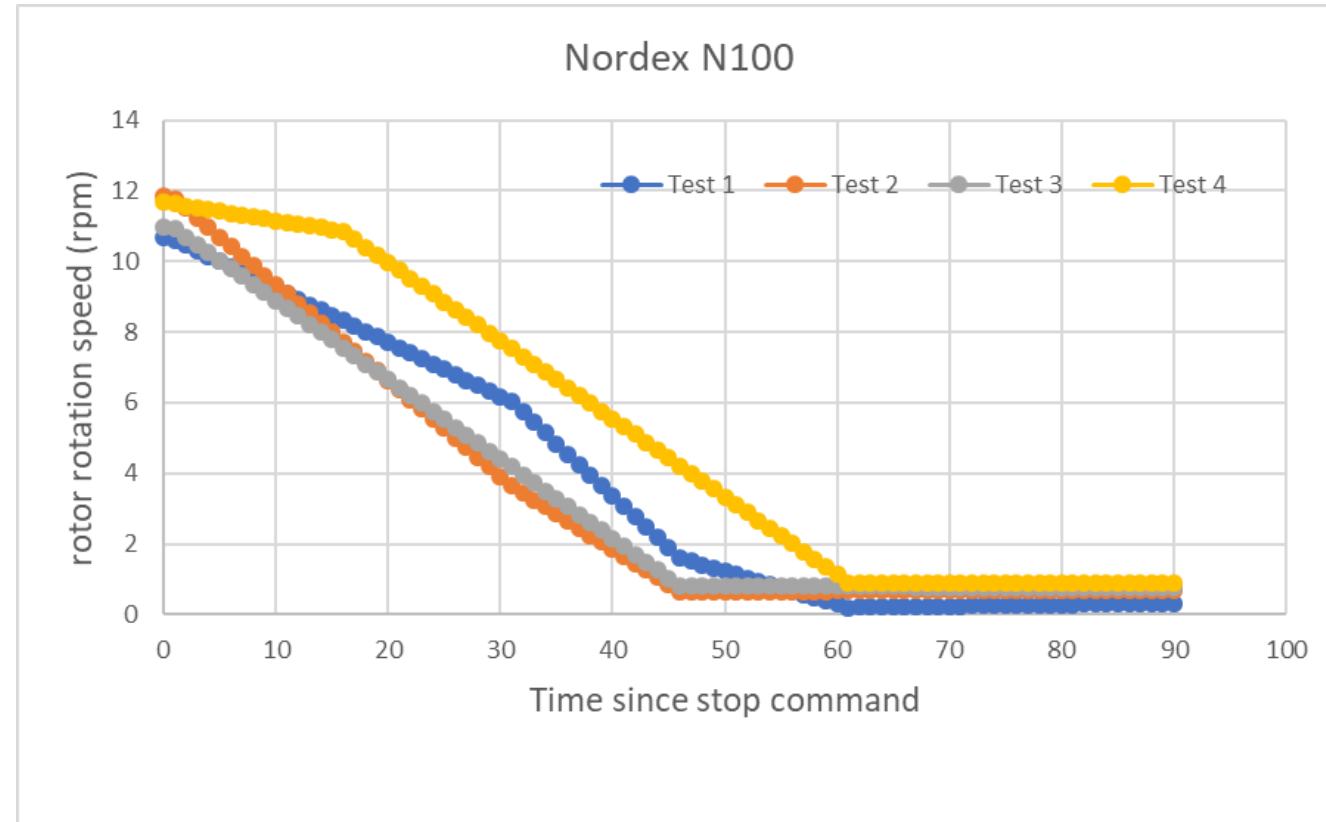
Users: Environmental Impact Assessment companies, detection-device makers, turbine makers, State authorities



What factors affect shutdown duration of turbine T_{rotor} ?

Protocol of tests of T_{rotor}

- Record rotation speed during 90 s after shutdown command
- 7 operators made 137 tests (10 models of turbines)



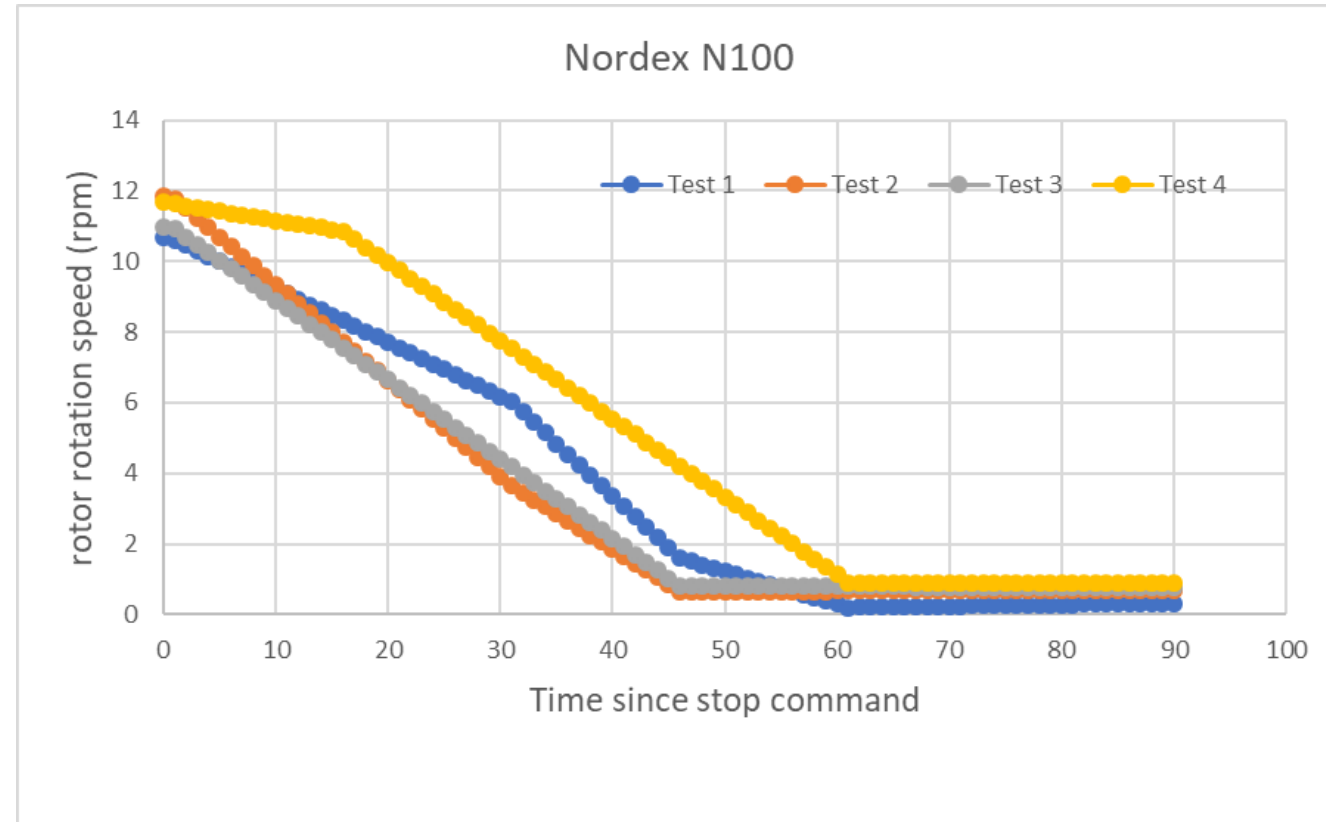
What factors affect shutdown duration of turbine T_{rotor} ?

1. Probability to reach a shutdown threshold (3 or 2 rpm)

- 3 rpm: 93% tests reached threshold
- 2 rpm: 84% tests reached threshold

⇒ Effect of 3 parameters:

- Type of machine
- Blade length
- Initial wind speed



What factors affect shutdown duration of turbine T_{rotor} ?

2. Duration to reach a shutdown threshold (3 or 2 rpm)

- 3 rpm: Duration $T_{\text{rotor}} = 32.2 \pm 13.5$ s (max 55 s)
- 2 rpm: Duration $T_{\text{rotor}} = 38.8 \pm 14.5$ s (max 65 s)

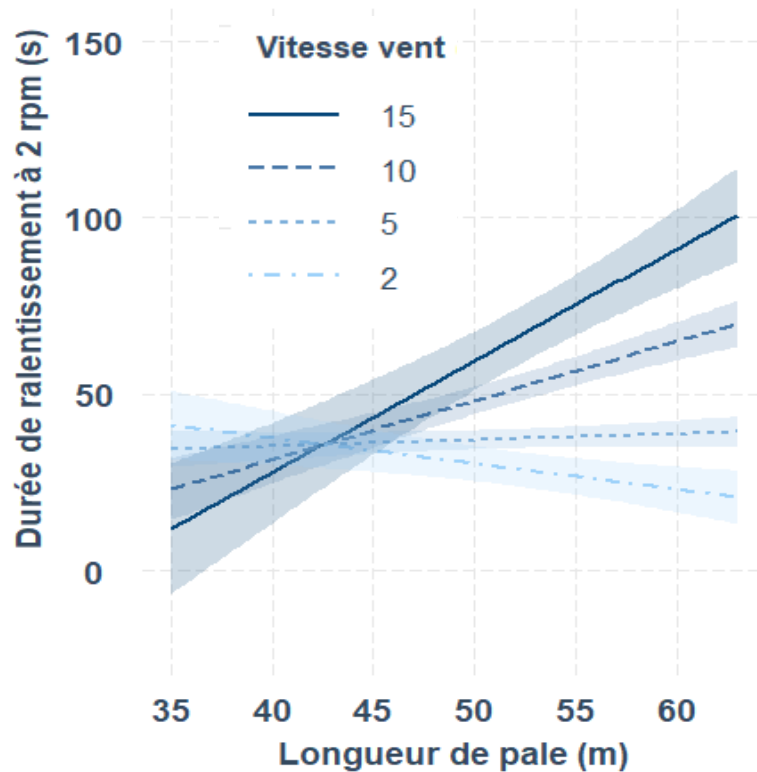
→ Interaction type machine, blade length and initial wind speed

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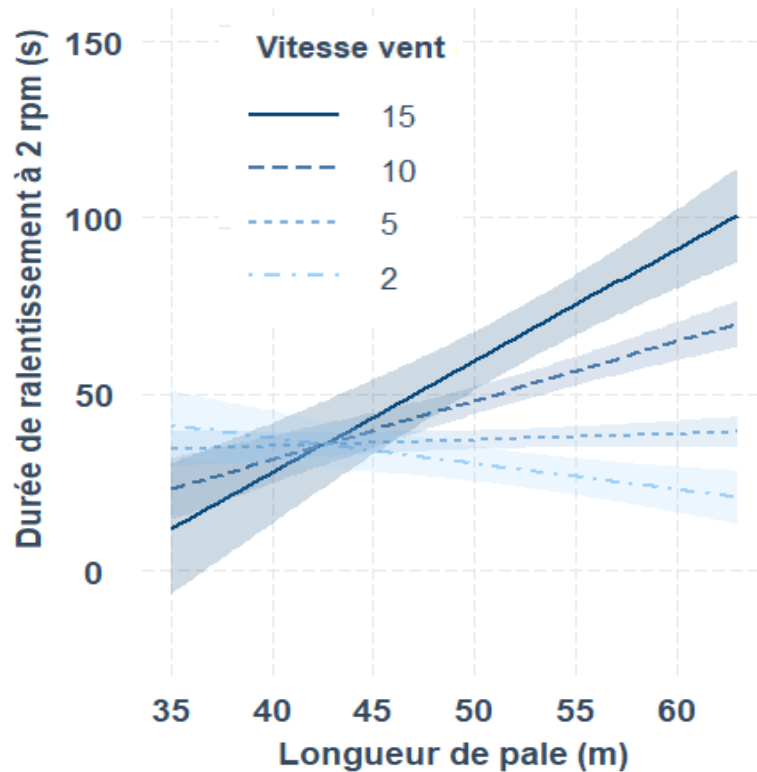
- *High wind speed*: shutdown duration shorter for short blades
- *Low wind speed*: similar shutdown duration for short / long blades

What factors affect shutdown duration of turbine T_{rotor} ?

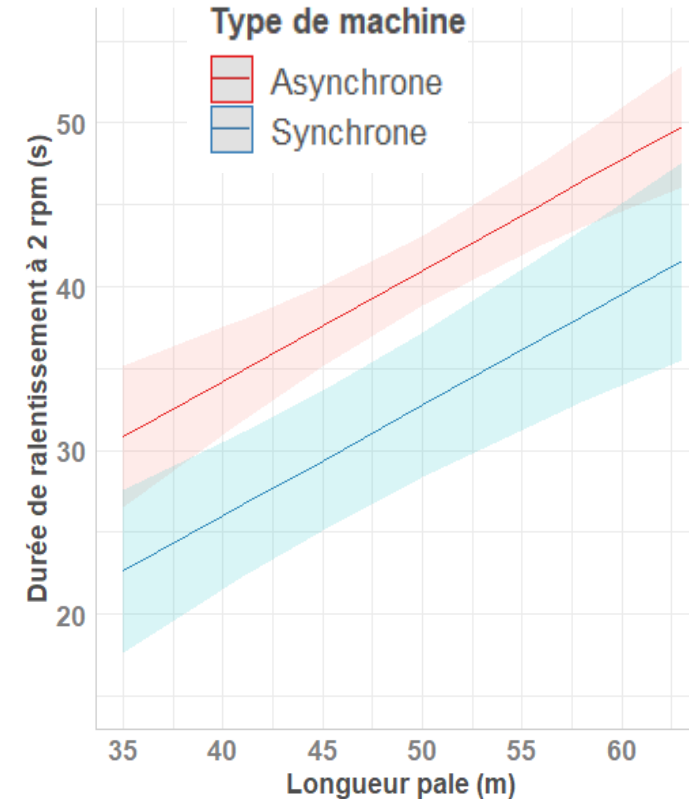
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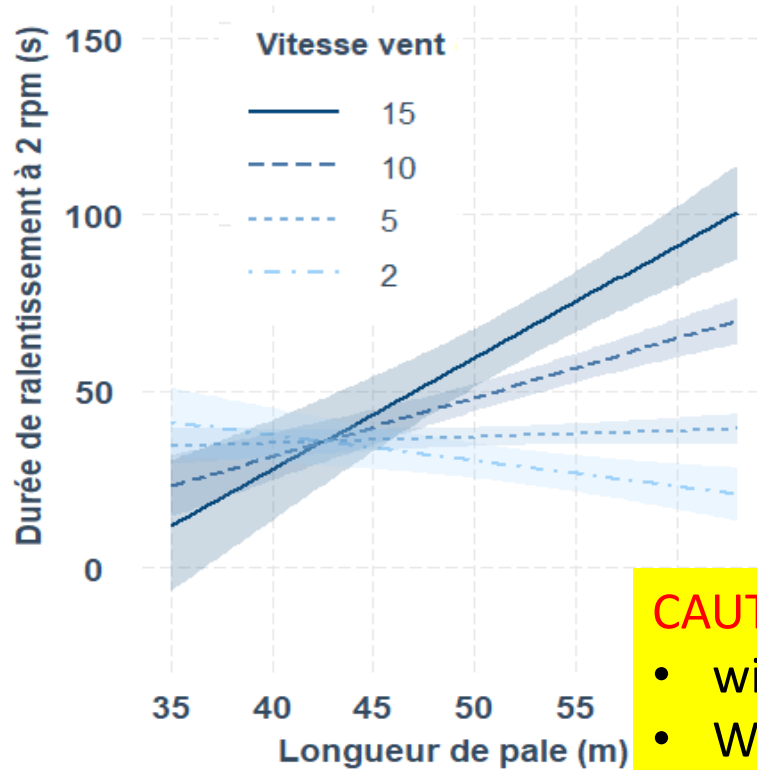


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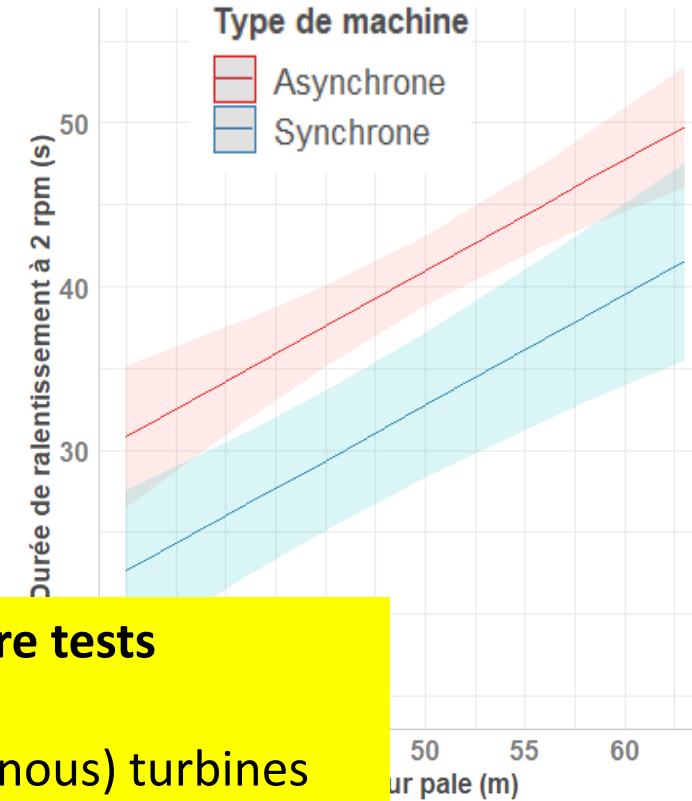
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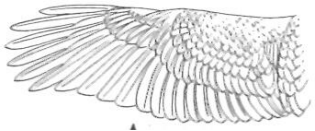
CAUTION: unbalanced sample of tests: **need more tests**

- with wind speed > 10 m.s⁻¹
- With large (synchronous) and small (asynchronous) turbines

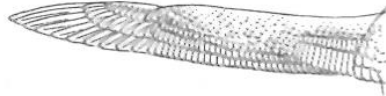
What factors affect bird flight speed?

Bird morphology & Flight type

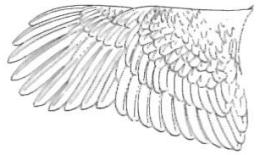
Slotted High-Lift Wing



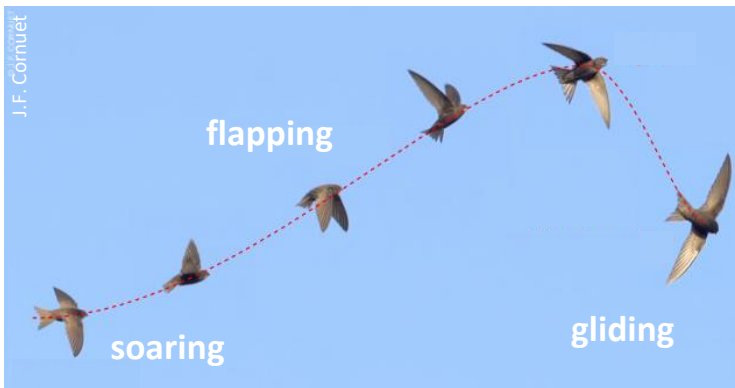
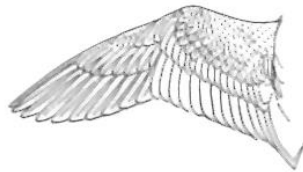
High-Aspect-Ratio Wing



Elliptical Wing



High-Speed Wing



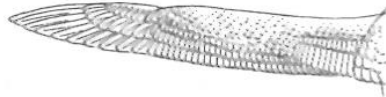
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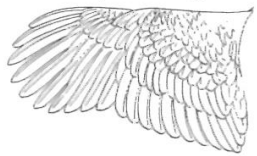
Slotted High-Lift Wing



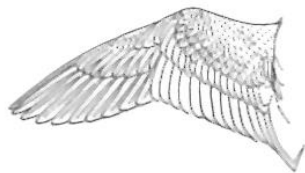
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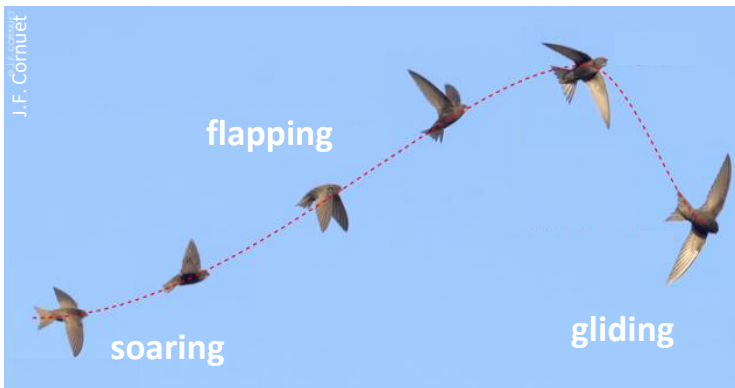


Environmental conditions



Wind speed
and direction

Topography



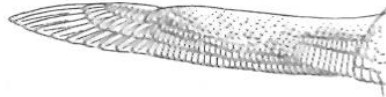
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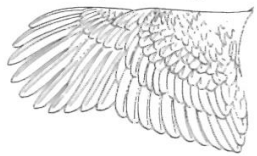
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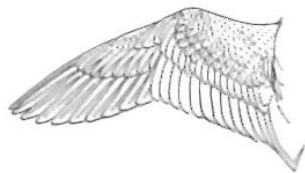
High-Aspect-Ratio Wing



Elliptical Wing



High-Speed Wing



Environmental conditions



Wind speed and direction

Topography



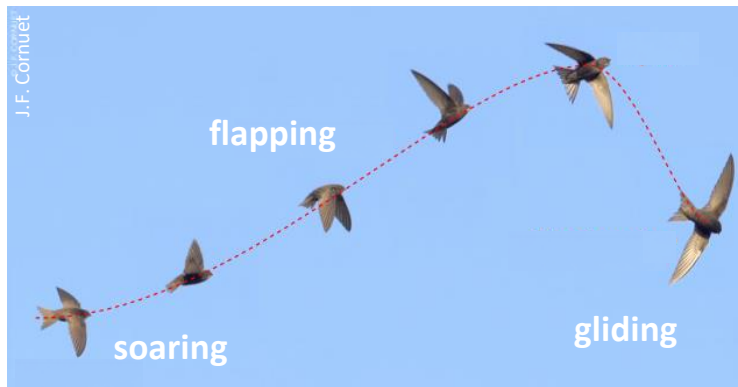
Motivation, context

Local flight



Steve Herring (cc by-nd)

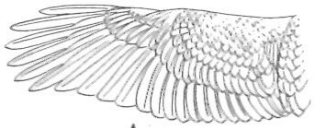
Migratory flight



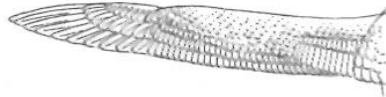
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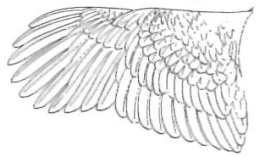
Slotted High-Lift Wing



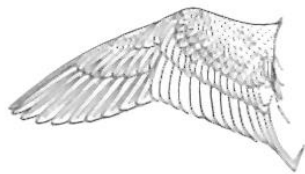
High-Aspect-Ratio Wing



Elliptical Wing



High-Speed Wing



Environmental conditions



Wind speed and direction

Topography



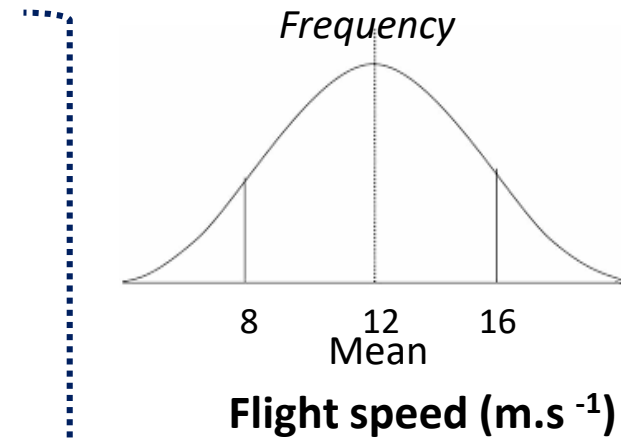
Motivation, context



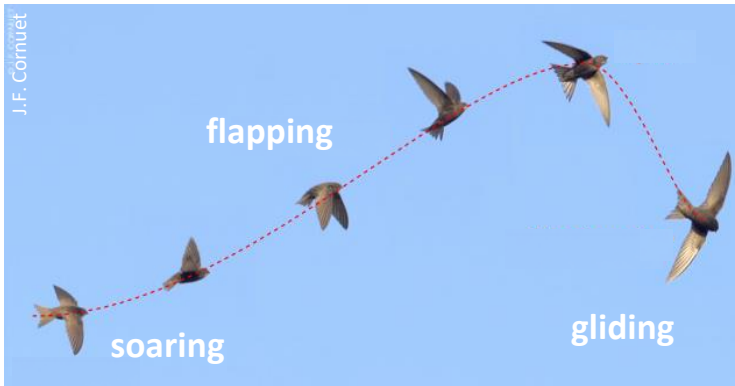
Local flight

Steve Herring (cc by-nd)

Migratory flight



Large variability of flight speed within species



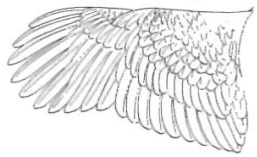
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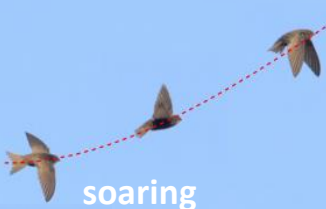


Elliptical Wing



J.F. Cornuet

flapping



soaring

mapeY Note de synthèse **Mai 2021**

Projet de recherche
« Réduction de la Mortalité Aviaire dans les Parcs Éoliens en Exploitation »

Déterminer les distances de détection minimales des oiseaux pour réduire les risques de collision avec les installations éoliennes :
Synthèse des connaissances relatives au vol et aux vitesses de vol des oiseaux.

Julie Fluhr, Olivier Duriez¹

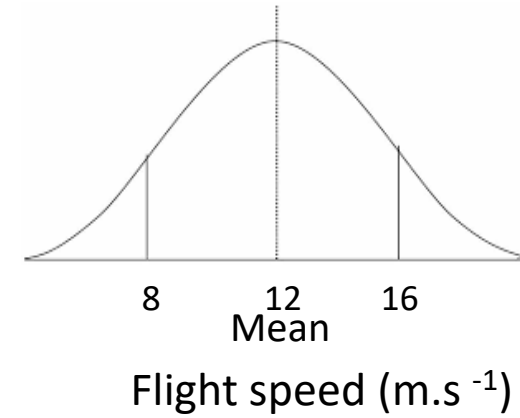
¹ Centre d'Ecologie Fonctionnelle et Evolutive, Univ. Montpellier, CNRS UMR5175, EPHE-PSL University, IRD, Univ. Paul Valéry Montpellier 3, Montpellier, France — équipe de recherche du projet MAPE (Mortalité Aviaire dans les Parcs Éoliens terrestres en exploitations)

Context

Local flight

Herring (cc by-nd)

Flight



Large variability of flight speed within species

More information on technical note
<https://mape.cnrs.fr/fr/valorisation-scientifique>



What factors affect bird flight speed?

Database of flight speed for 163 bird species

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Database of flight speed for 163 bird species

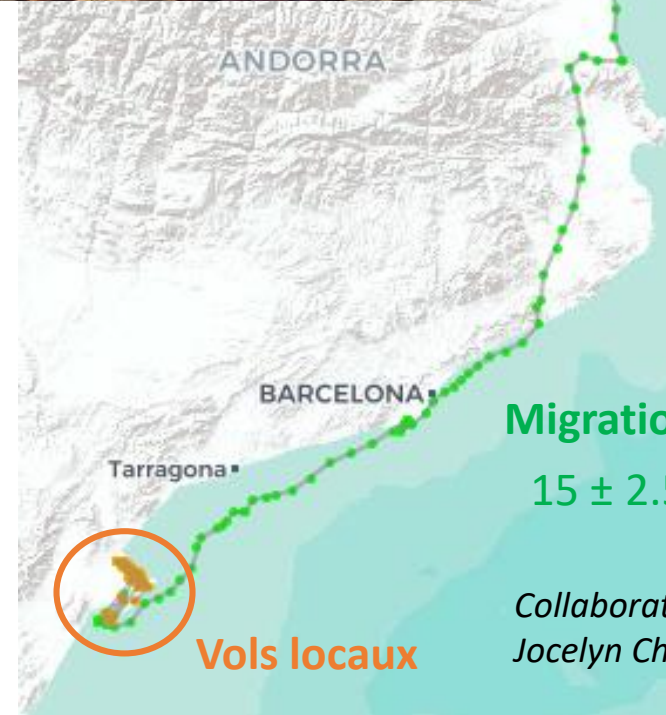
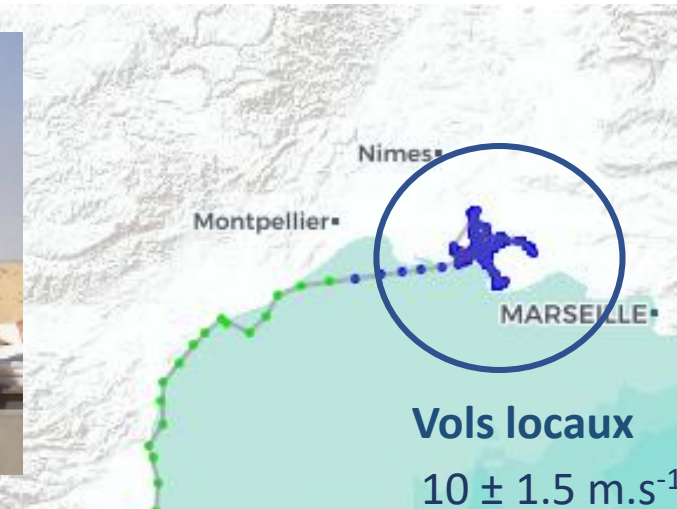
- Litterature search of published values
 - **139 species** recorded remotely by radar / Ornithodolite (mostly migration)
 - **6 species** recorded by telemetry (GPS / VHF)



What factors affect bird flight speed?

Database of flight speed for 163 bird species

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 - **24 species** (mostly local context + some migration)



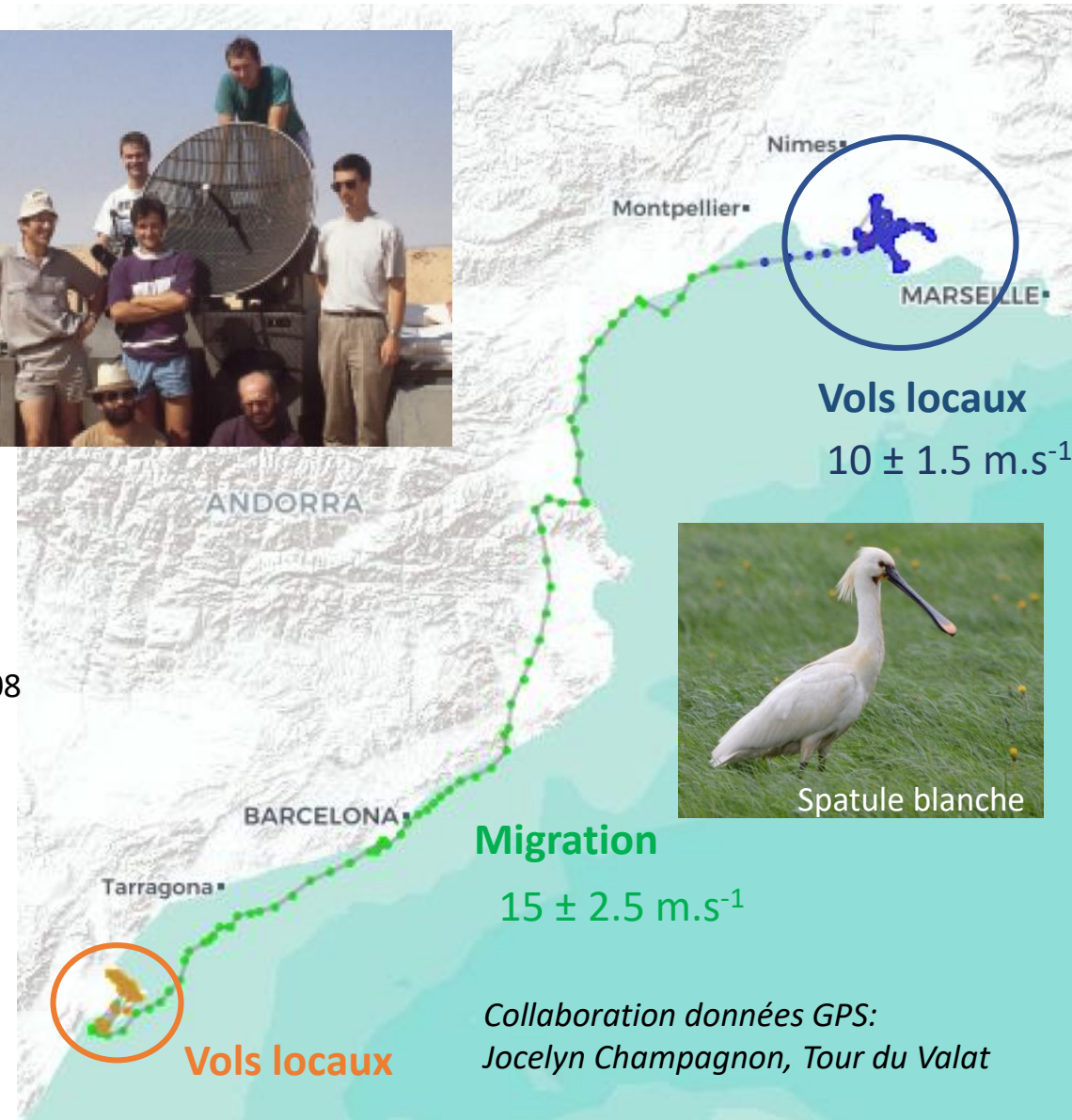
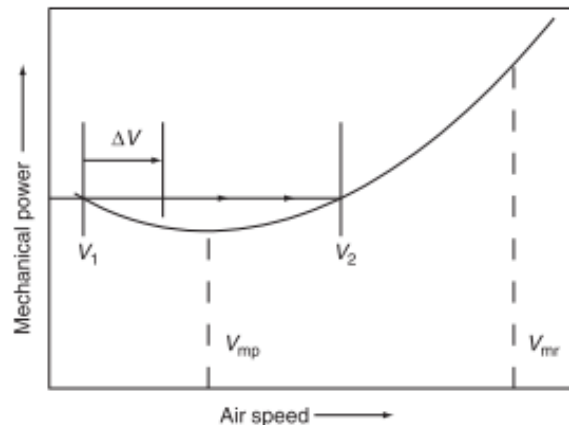
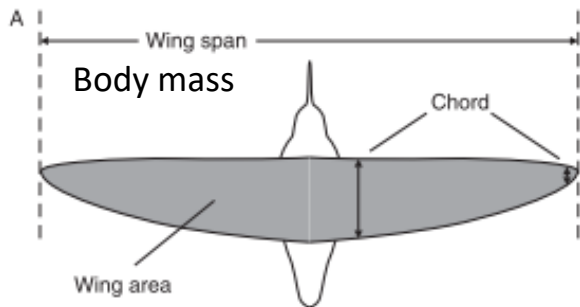
Migration
 $15 \pm 2.5 \text{ m.s}^{-1}$

*Collaboration données GPS:
 Jocelyn Champagnon, Tour du Valat*

What factors affect bird flight speed?

Database of flight speed for 163 bird species

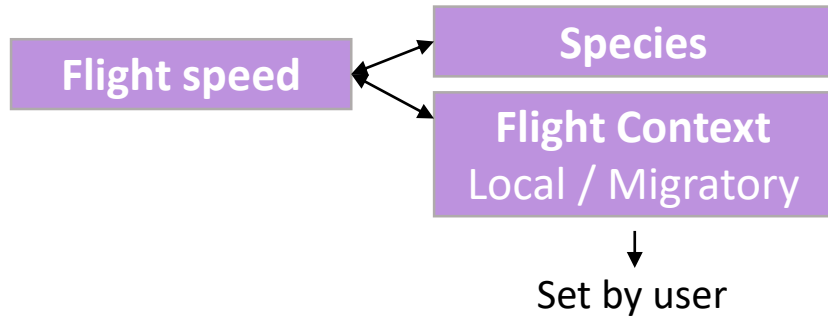
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- Analysis of unpublished data from GPS tracking
 - 24 species (mostly local context + some migration)
- Analysis of theoretical flight speed
 - **17 species**, simulated with Flight program, Pennycuick 2008



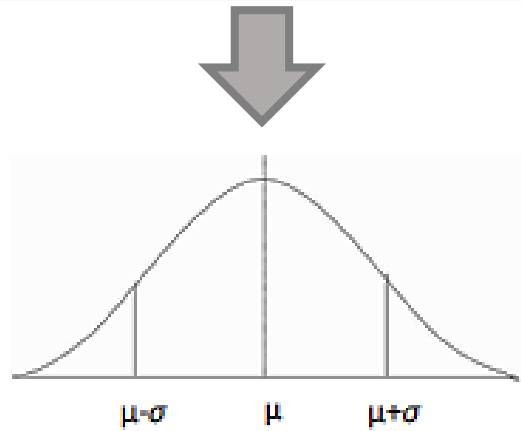
Collaboration données GPS:
Jocelyn Champagnon, Tour du Valat

Web application EoIDist: principle and work flow

INPUT



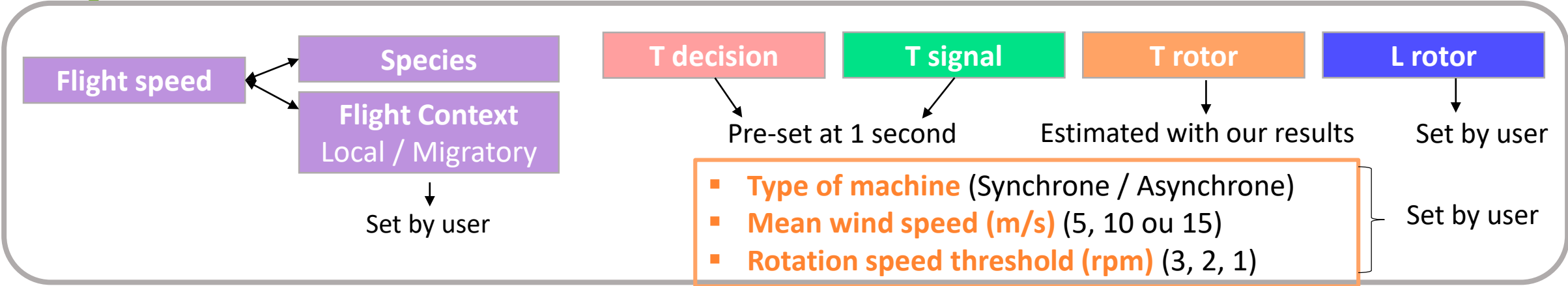
OUTPUT



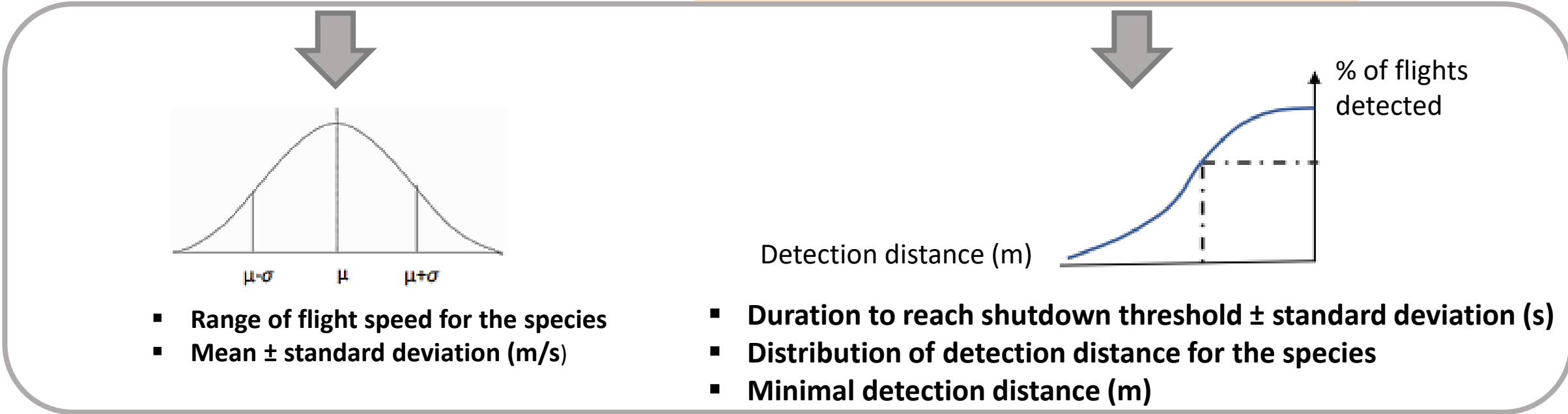
- Range of flight speed for the species
- Mean \pm standard deviation (m/s)

Web application EolDist: principle and work flow

INPUT



OUTPUT



Demo of web application EoIDist

Exemple 1: Griffon vulture *Gyps fulvus*

Large soaring raptor (8 kg)

One of the main victim of collisions in Spain



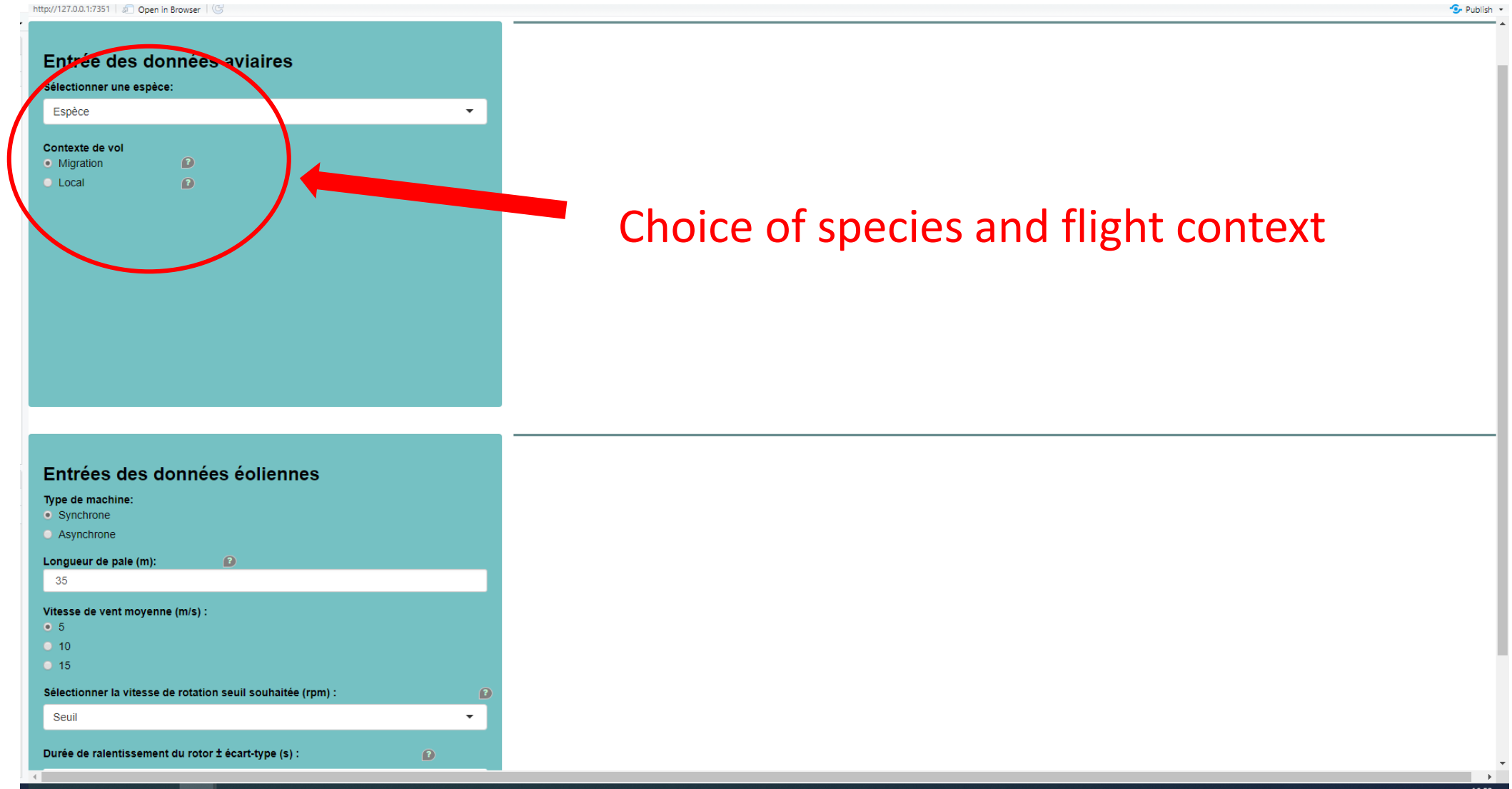
Exemple 2: Lesser kestrel *Falco naumanni*

Small raptor (200 g), active flier

One of the main victim of collisions in southern France



Demo of web application EolDist



Choice of species and flight context

Demo of web application EoIDist

Exemple 1: Griffon vulture *Gyps fulvus*

Exemple 2: Lesser kestrel *Falco naumanni*

Entrée des données aviaires

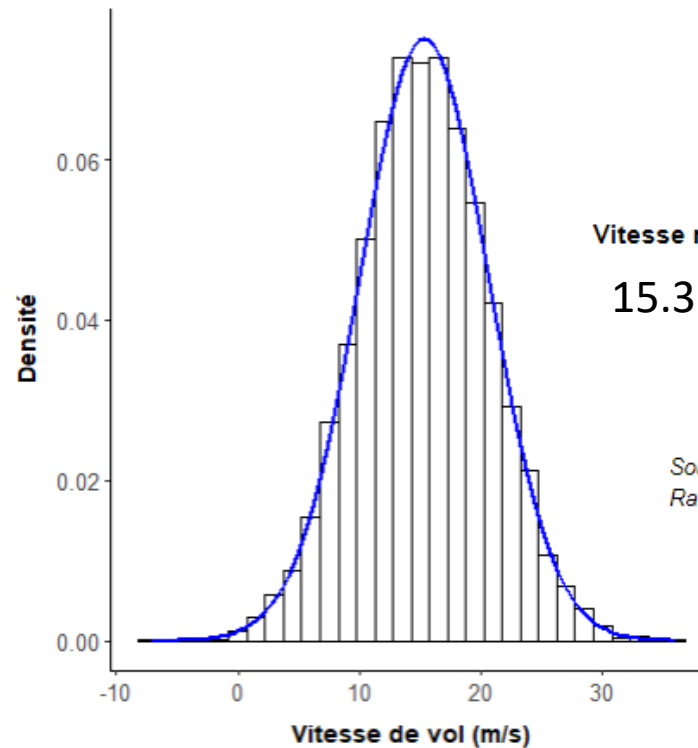
Sélectionner une espèce:

Vautour fauve (*Gyps fulvus*) ▼

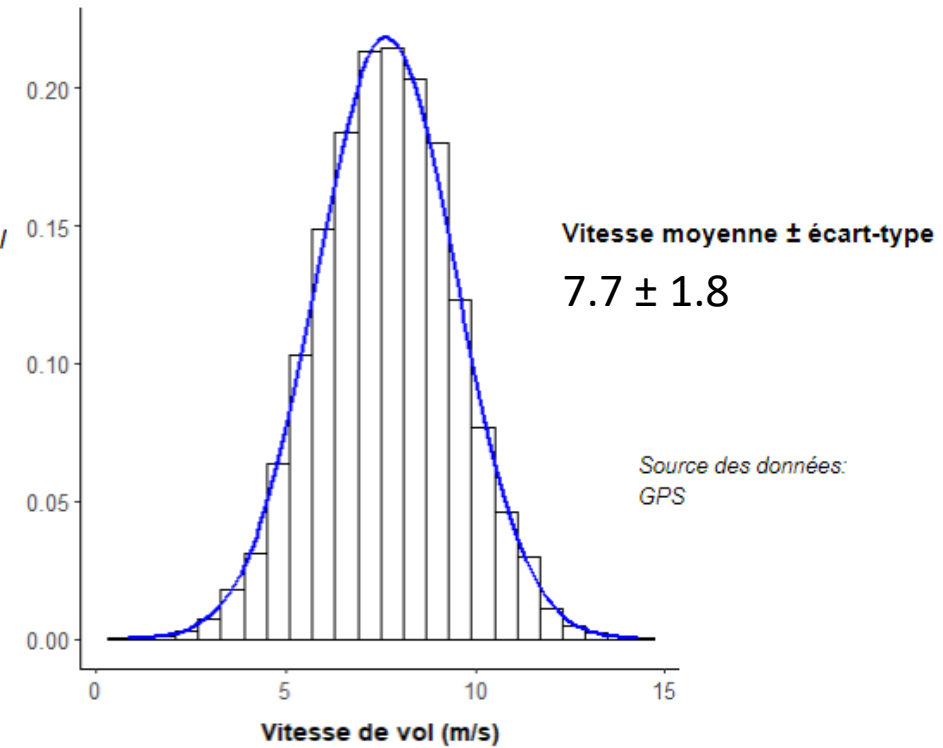
Contexte de vol

- Migration ?
- Local ?

Vautour fauve (*Gyps fulvus*) , Local



Faucon crécerellette (*Falco naumanni*) , Local



Demo of web application EolDist

Entrée des données aviaires

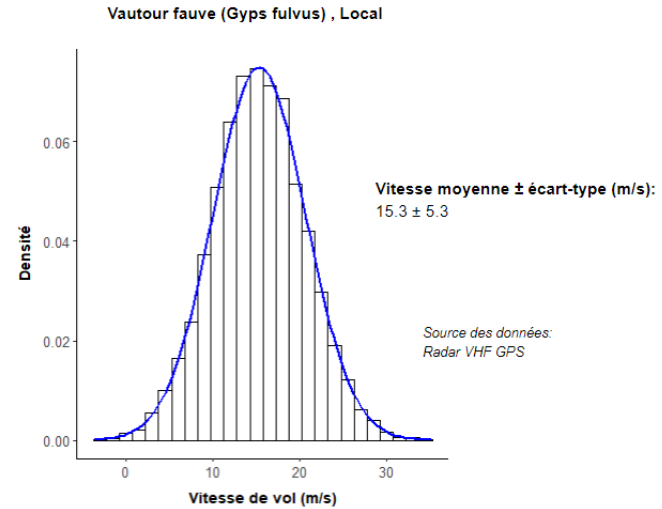
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Contexte de vol

Migration ?

Local ?



Entrées des données éoliennes

Type de machine:

Synchronne

Asynchrone

Longueur de pale (m):

45

Vitesse de vent moyenne (m/s) :

5

10

15

Sélectionner la vitesse de rotation seuil souhaitée (rpm) :

Seuil

Durée de ralentissement du rotor \pm écart-type (s) :

Choice of

- turbine features (synchronne/asynchrone), blade length
- wind speed
- Shutdown threshold

Demo of web application EolDist

Exemple 1: Griffon vulture *Gyps fulvus*

Entrées des données éoliennes

Type de machine:

- Synchrone
- Asynchrone

Longueur de pale (m):

Vitesse de vent moyenne (m/s):

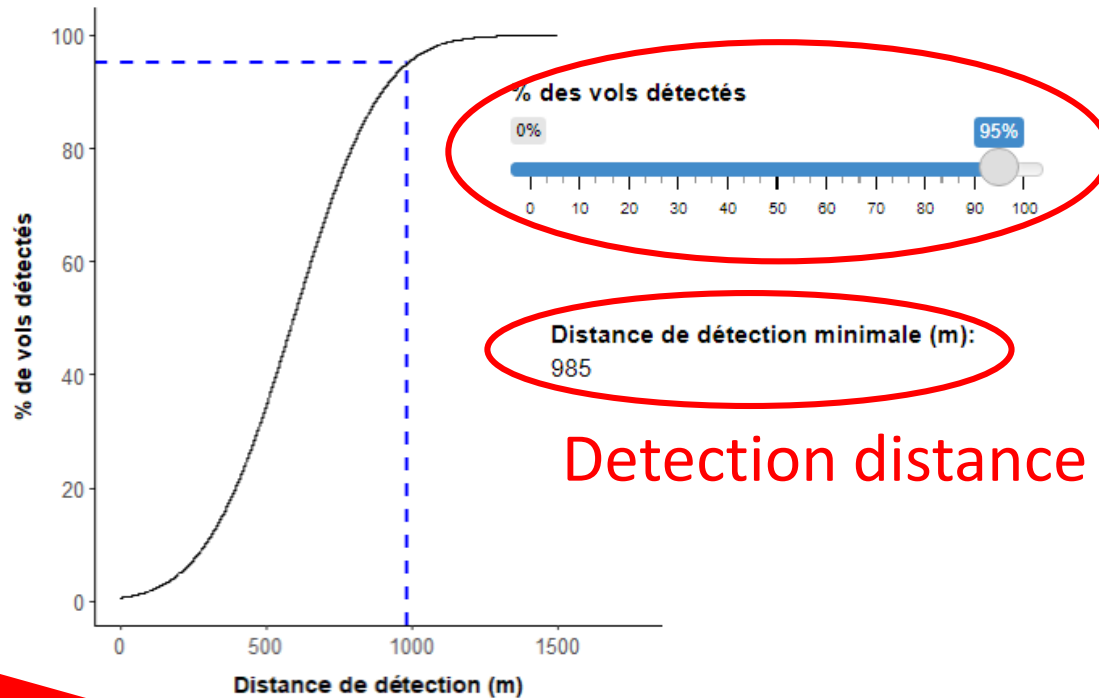
- 5
- 10
- 15

Sélectionner la vitesse de rotation seuil souhaitée (rpm):

Durée de ralentissement du rotor ± écart-type (s):

Distance de détection de l'espèce

Vautour fauve (*Gyps fulvus*) , Vitesse de rotation seuil : 3 rpm



Choice of % of flight detected

Duration to reach shutdown threshold

Demo of web application EolDist

Exemple 1: Griffon vulture *Gyps fulvus*

Machine synchrone
45 m blade length
Threshold shutdown 3 rpm
95% flight detected

Exemple 2: Lesser kestrel *Falco naumanni*

Entrées des données éoliennes

Type de machine:
 Synchrone
 Asynchrone

Longueur de pale (m):

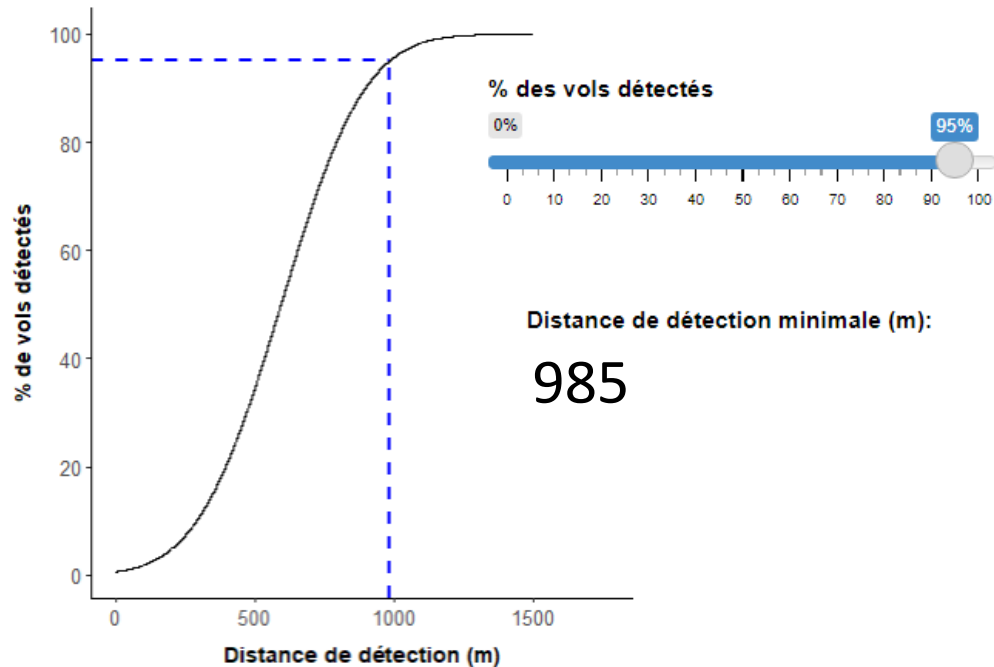
Vitesse de vent moyenne (m/s):
 5
 10
 15

Sélectionner la vitesse de rotation seuil souhaitée (rpm):

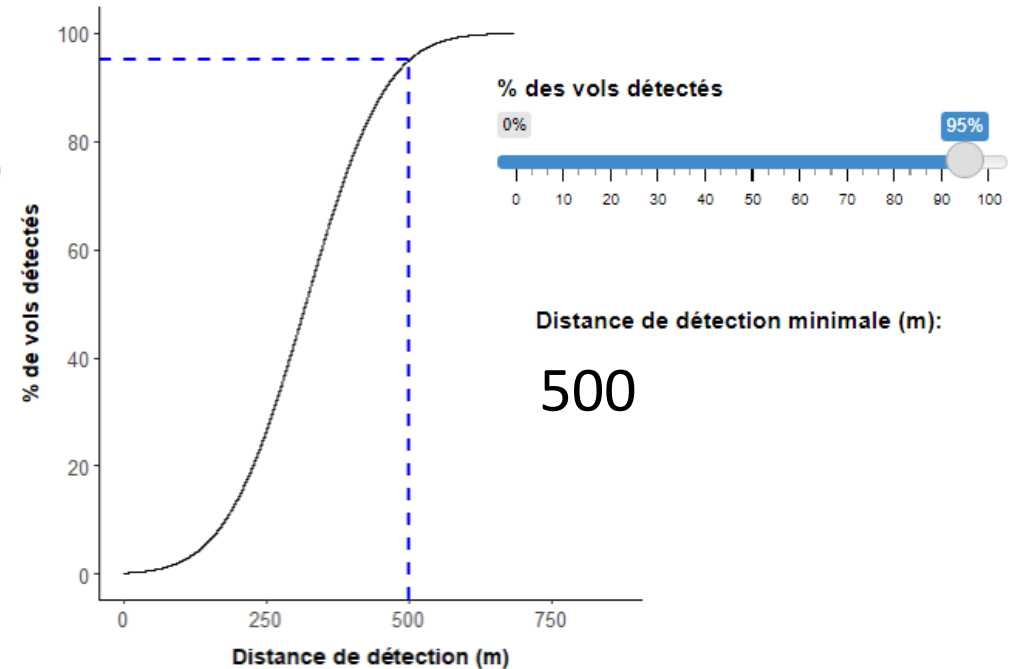
Durée de ralentissement du rotor \pm écart-type (s):

Distance de détection de l'espèce

Vautour fauve (*Gyps fulvus*) , Vitesse de rotation seuil : 3 rpm



Faucon crécerellette (*Falco naumanni*) , Vitesse de rotation seuil : 3 rpm



Demo of web application EolDist

Exemple 1: Griffon vulture *Gyps fulvus*

Machine synchrone
 45 m blade length
Threshold shutdown 2 rpm
 95% flight detected

Exemple 2: Lesser kestrel *Falco naumanni*

Entrées des données éoliennes

Type de machine:
 Synchrone
 Asynchrone

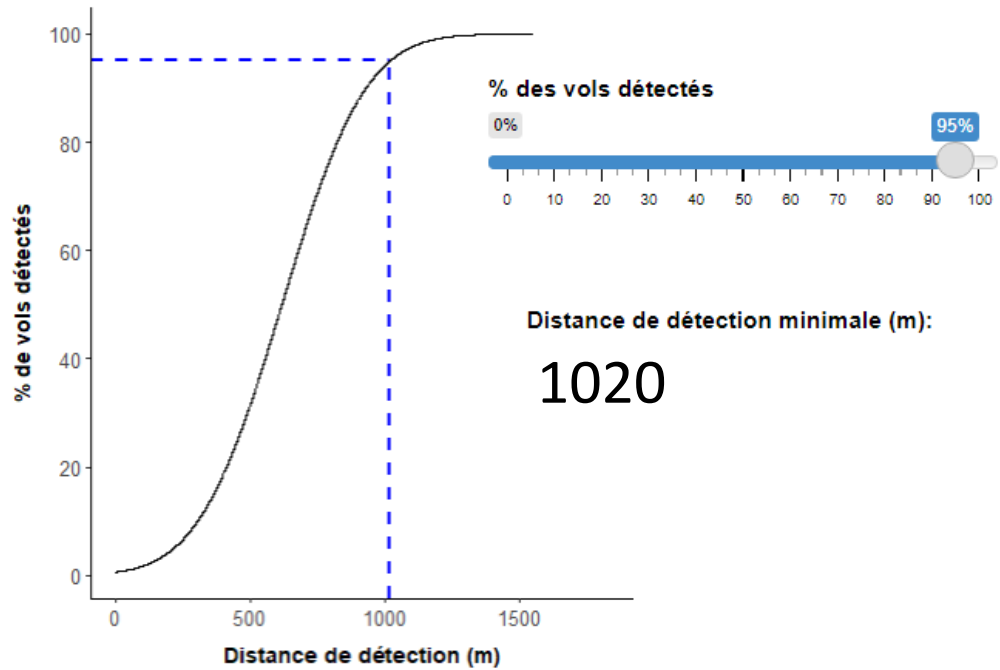
Longueur de pale (m):

Vitesse de vent moyenne (m/s):
 5
 10
 15

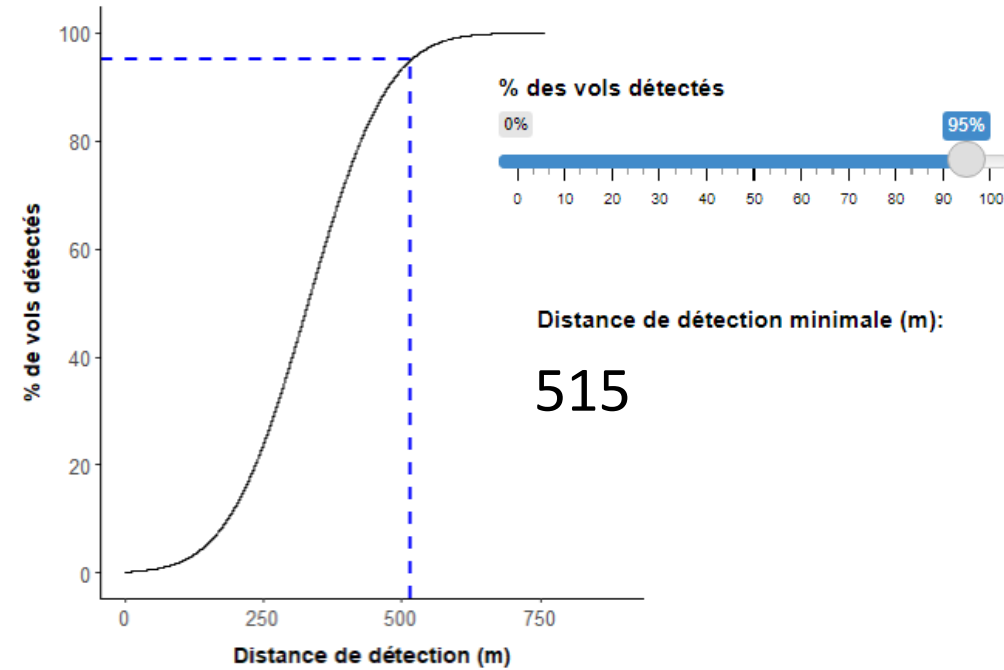
Sélectionner la vitesse de rotation seuil souhaitée (rpm):

Durée de ralentissement du rotor \pm écart-type (s):

Vautour fauve (*Gyps fulvus*) , Vitesse de rotation seuil : 2 rpm



Faucon crécerellette (*Falco naumanni*) , Vitesse de rotation seuil : 2 rpm



Demo of web application EolDist

Exemple 1: Griffon vulture *Gyps fulvus*

Machine synchrone
 45 m blade length
 Threshold shutdown 2 rpm
50% flights detected

Exemple 2: Lesser kestrel *Falco naumanni*

Entrées des données éoliennes

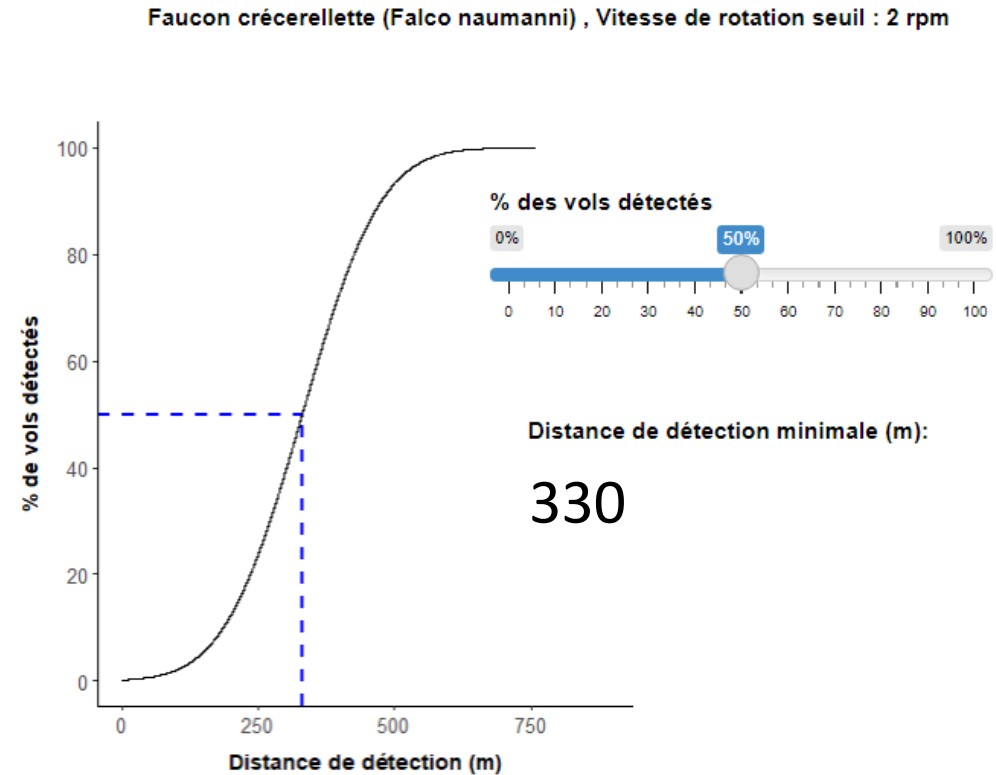
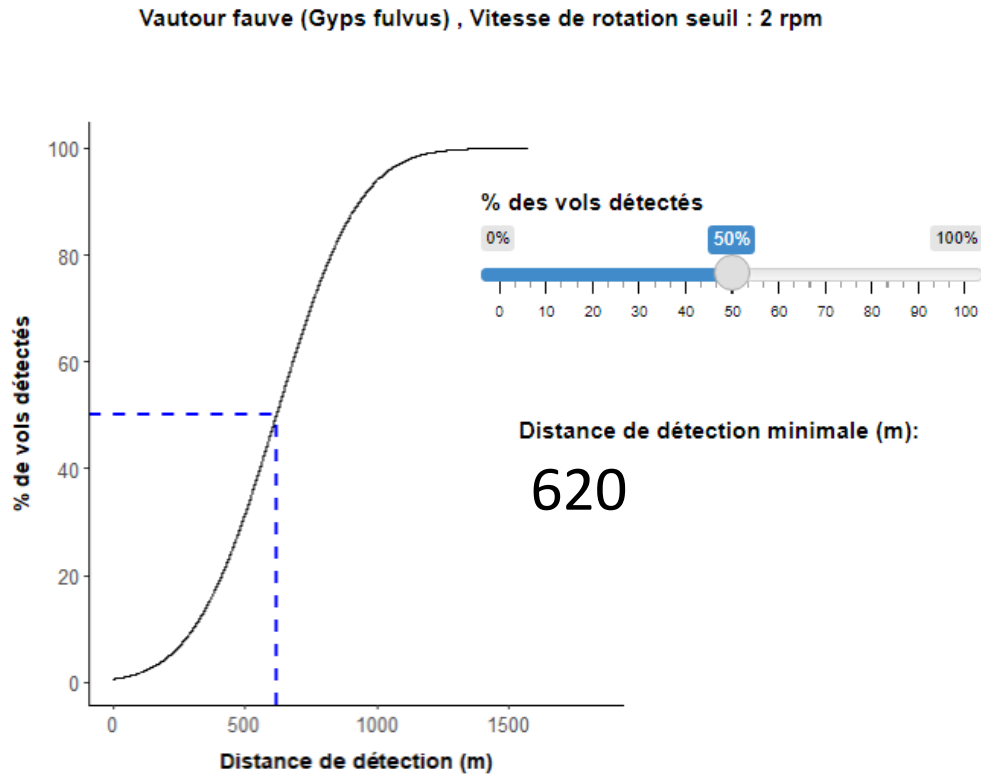
Type de machine:
 Synchrone
 Asynchrone

Longueur de pale (m):

Vitesse de vent moyenne (m/s):
 5
 10
 15

Sélectionner la vitesse de rotation seuil souhaitée (rpm):

Durée de ralentissement du rotor ± écart-type (s):



Demo of web application EoIDist

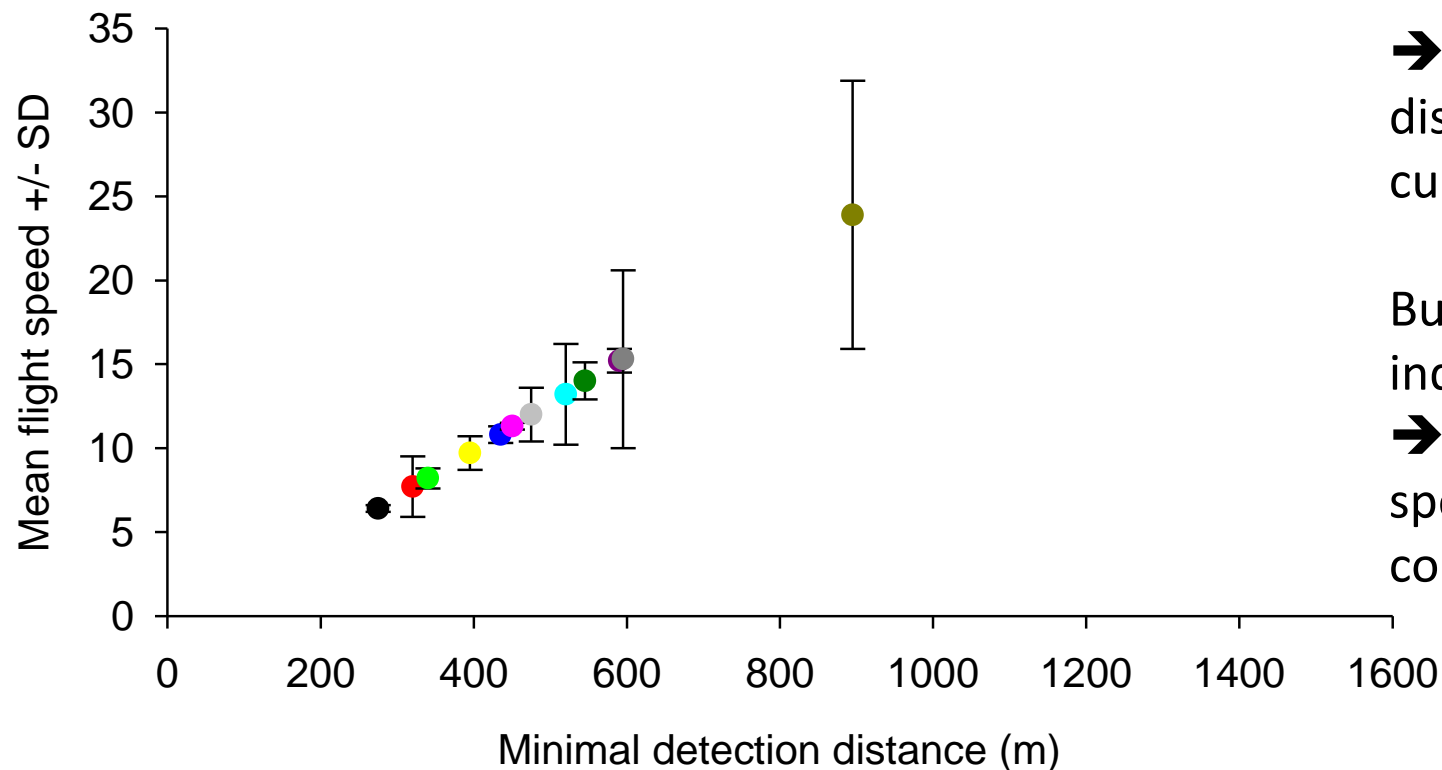
Simulations for 12 species of conservation concern (PNA) → importance of the detection threshold

Machine synchrone, blade 45m, wind 10 m/s,
 threshold 3 rpm (51 km/h) **detection 50% of flights**

Shutdown duration: 33.8 ± 2.4 s

Local flight context

■	Circus pygargus
■	Falco naumanni
■	Milvus milvus
■	Platalea leucorodia
■	Ciconia nigra
■	Grus grus
■	Tetrax tetrax
■	Neophron percnopterus
■	Haliaeetus albicilla
■	Cygnus columbianus
■	Gyps fulvus
■	Falco peregrinus



→ Minimum detection distances globally suitable for current detection devices

But Risk of collision for 50% of individuals

→ Ethically impossible for species of conservation concern

Demo of web application EoIDist

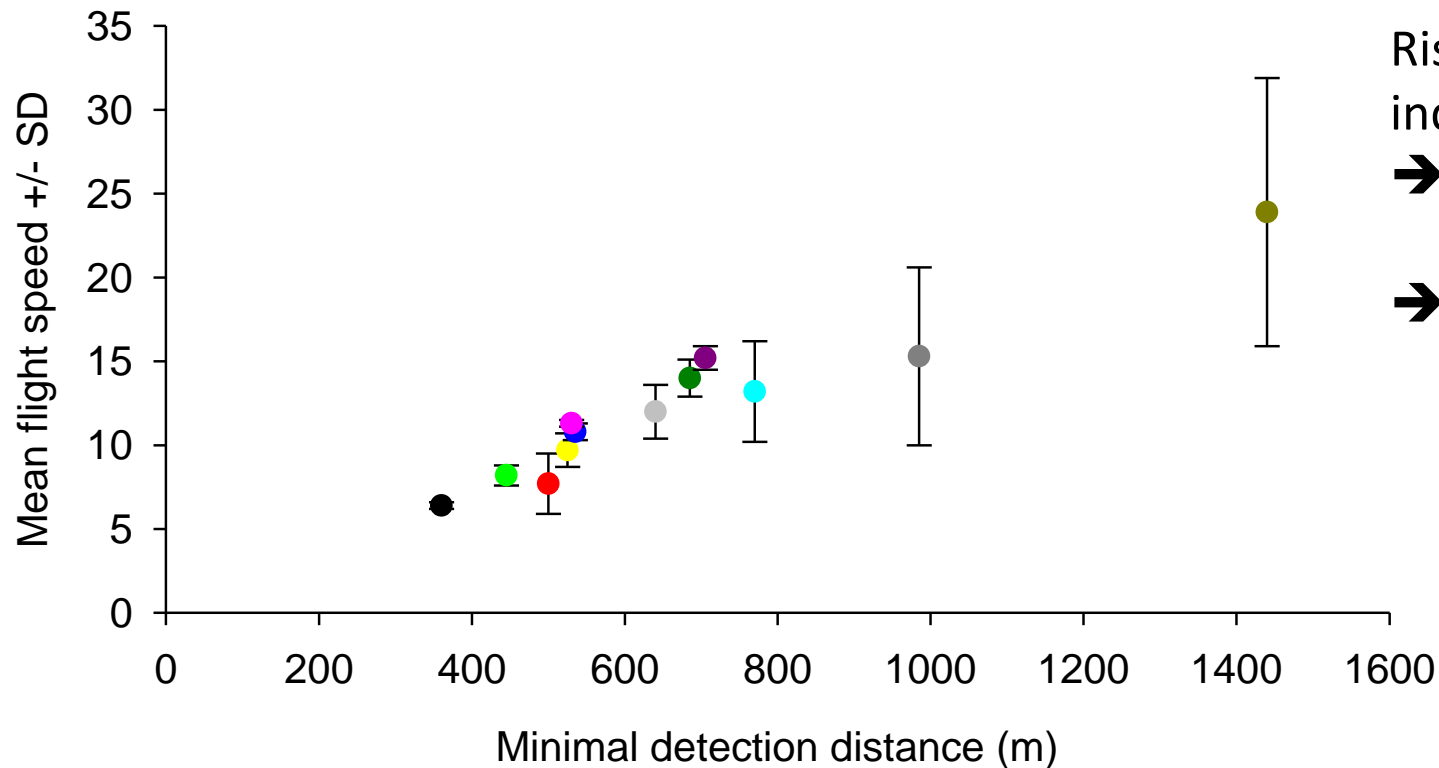
Simulations for 12 species of conservation concern (PNA) → importance of the detection threshold

Machine synchrone, blade 45m, wind 10 m/s, threshold 3 rpm (51 km/h), **detection 95% of flights**

Shutdown duration: 33.8 ± 2.4 s

Local flight context

Black	Circus pygargus
Red	Falco naumanni
Green	Milvus milvus
Yellow	Platalea leucorodia
Blue	Ciconia nigra
Magenta	Grus grus
Grey	Tetrax tetrax
Cyan	Neophron percnopterus
Dark Green	Haliaeetus albicilla
Purple	Cygnus columbianus
Light Grey	Gyps fulvus
Olive	Falco peregrinus



Risk of collision for 5% of individuals

→ Ethically suitable for rare species

→ Large increase (+35%) of minimal detection distance, difficult to satisfy with current devices

Demo of web application EoIDist

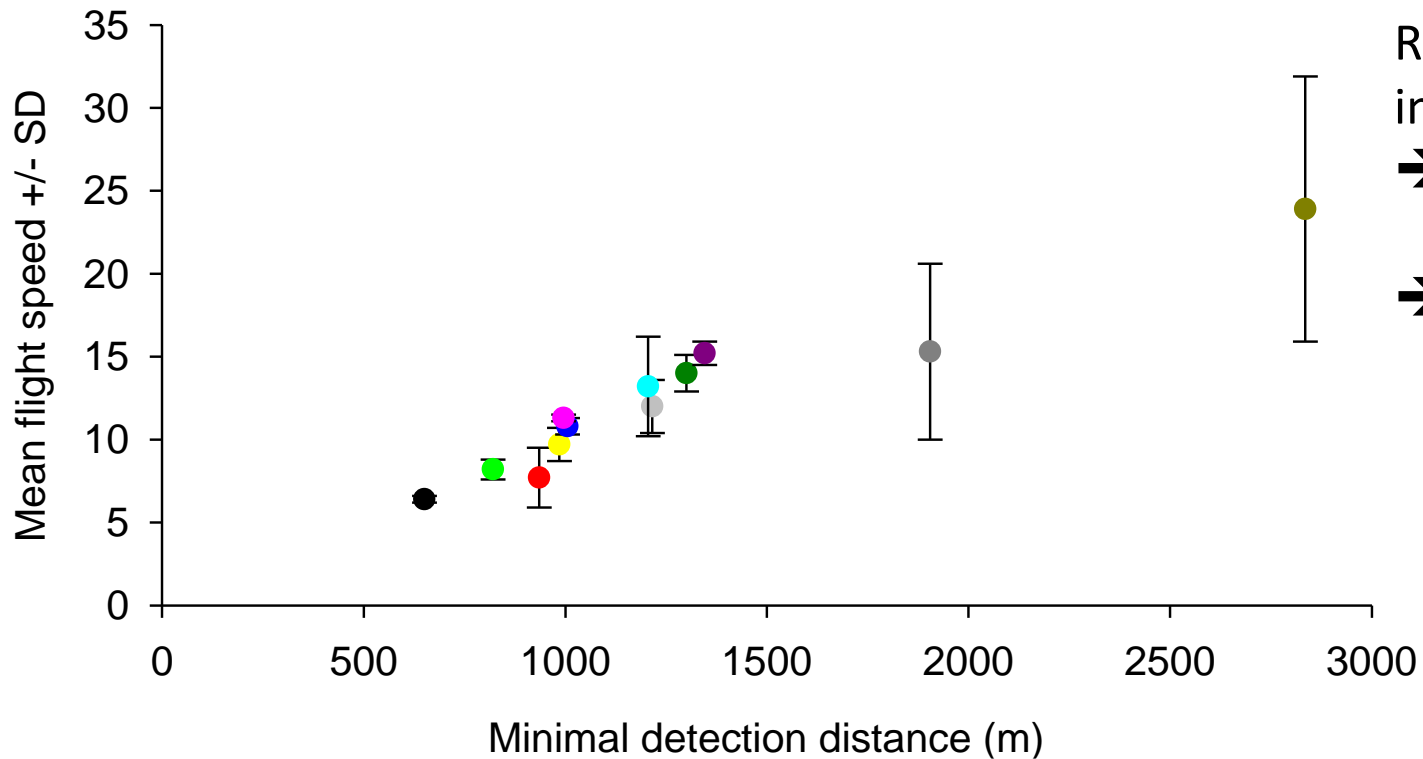
Simulations for 12 species of conservation concern (PNA) → importance of the detection threshold

Machine asynchrone, blade 63m, wind 10 m/s, threshold 2 rpm (50 km/h), detection 95% of flights

Shutdown duration: 69.9 ± 3.3 s

Local flight context

Black	Circus pygargus
Red	Falco naumanni
Green	Milvus milvus
Yellow	Platalea leucorodia
Blue	Ciconia nigra
Magenta	Grus grus
Grey	Tetrax tetrax
Cyan	Neophron percnopterus
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Risk of collision for 5% of individuals

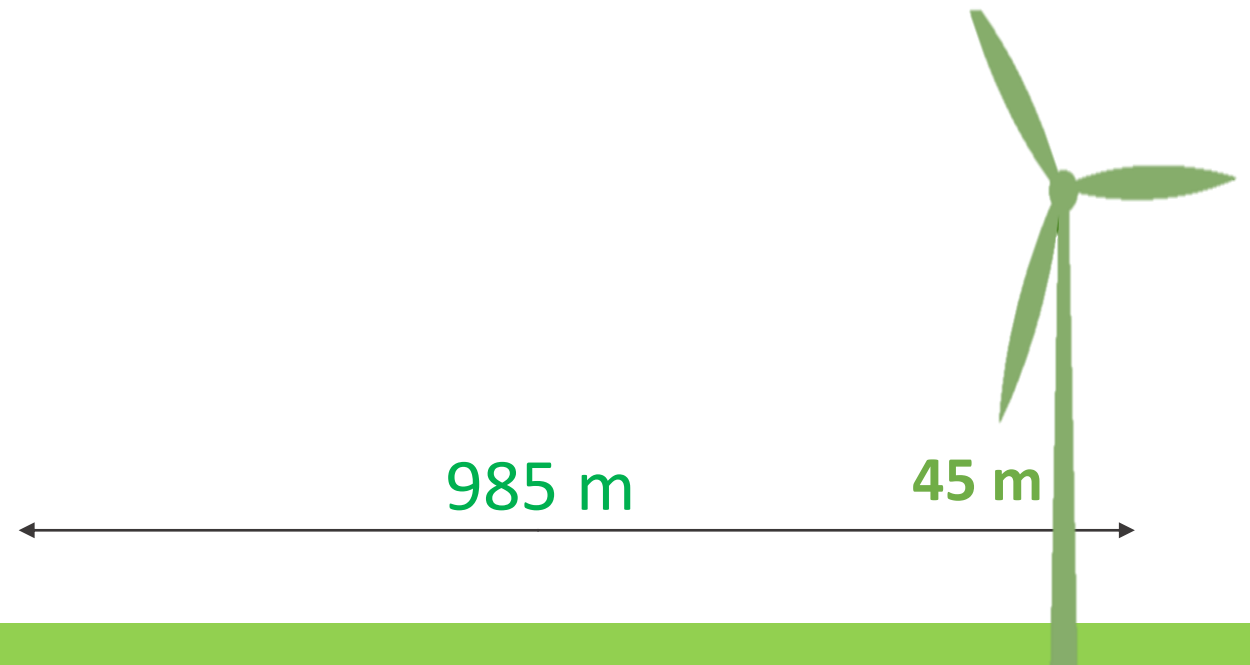
→ Ethically suitable for rare species

→ VERY Large increase of minimal detection distance

mape^Y Solutions of improvements for the current trend of size increase?

$$\text{Minimal distance detection} = (T_{\text{decision}} + T_{\text{signal}} + T_{\text{rotor}}) * \text{Flight speed}$$

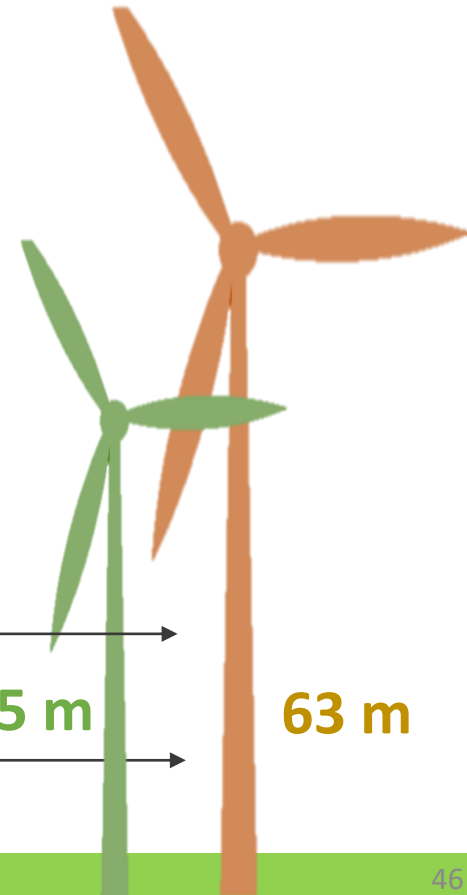
1 s **1 s** **34 s** **15.3 m.s⁻¹**



Solutions of improvements for the current trend of size increase?

$$\text{Minimal distance detection} = (T_{\text{decision}} + T_{\text{signal}} + T_{\text{rotor}}) * \text{Flight speed}$$

1 s	+	1 s	+	34 s)	*	15.3 m.s⁻¹
69 s							<u>1905 m</u>



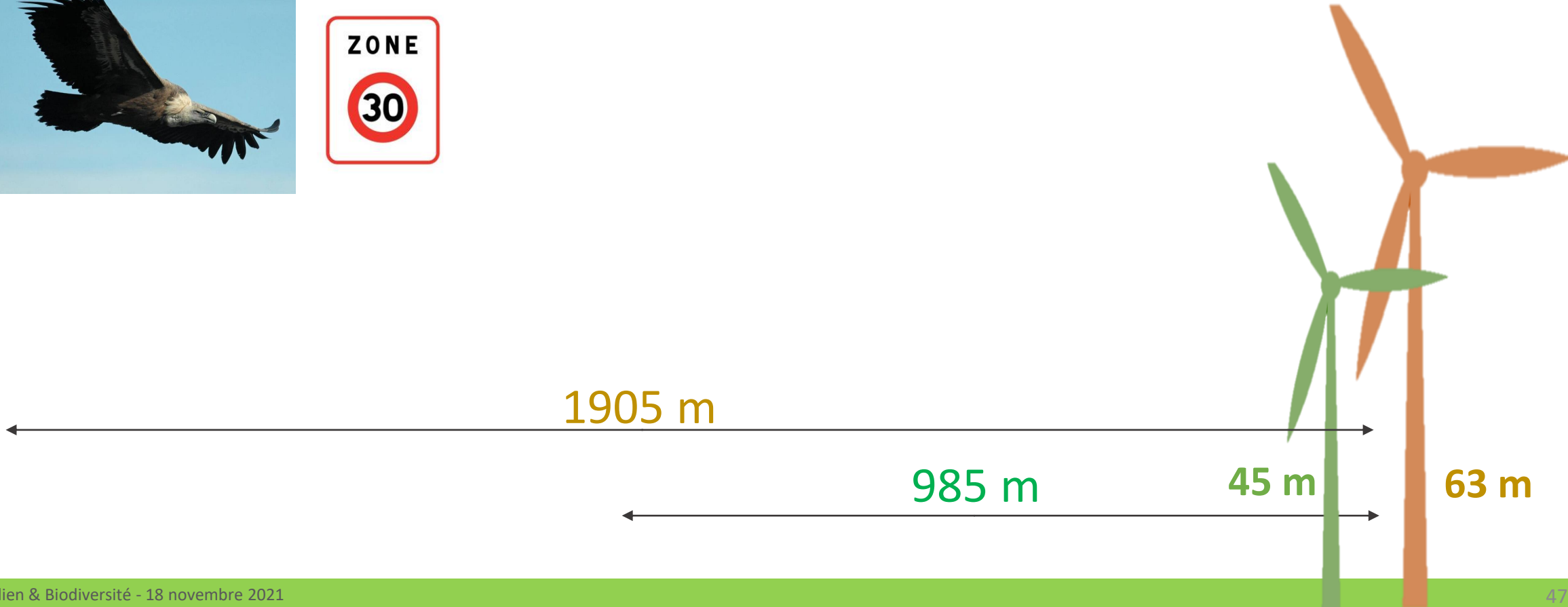
Solutions of improvements for the current trend of size increase?

$$\text{Minimal distance detection} = (T_{\text{decision}} + T_{\text{signal}} + T_{\text{rotor}}) * \text{Flight speed}$$

1 s	1 s	34 s	15.3 m.s^{-1}
		69 s	



Slow down bird flight speed?



Solutions of improvements for the current trend of size increase?

$$\text{Minimal distance detection} = (T_{\text{decision}} + T_{\text{signal}} + T_{\text{rotor}}) * \text{Flight speed}$$

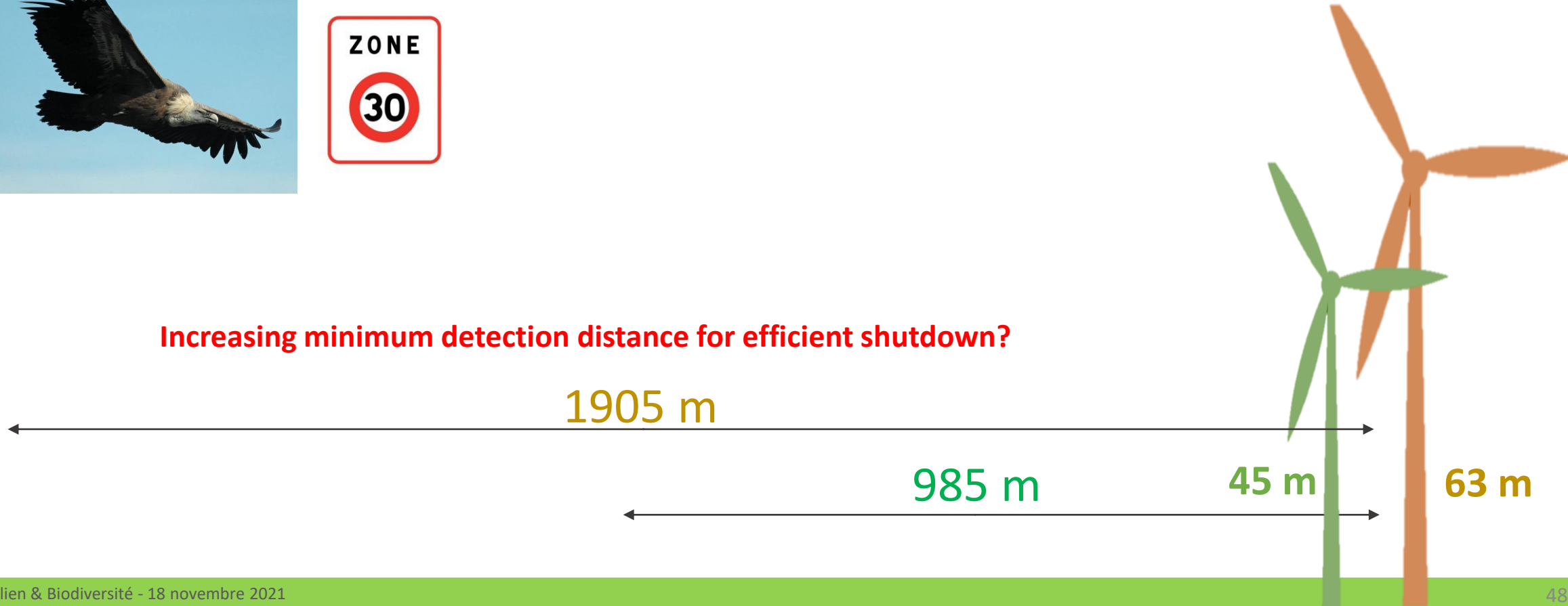
1 s	+	1 s	+	34 s)	*	15.3 m.s^{-1}
				69 s			15.3 m.s^{-1}



Slow down bird flight speed?



Increasing minimum detection distance for efficient shutdown?



Solutions of improvements for the current trend of size increase?

$$\text{Minimal distance detection} = (T_{\text{decision}} + T_{\text{signal}} + T_{\text{rotor}}) * \text{Flight speed}$$

1 s	1 s	34 s	15.3 m.s^{-1}
		69 s	



Slow down bird flight speed?



Reducing shutdown duration?

Increasing minimum detection distance for efficient shutdown?



Conclusion

- Web application EoIDist is simple and fonctionnal
 - Available online before December 2021
 - English version soon available

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- For state authorities and EIA companies → finding the best suitable detection device to protect local species of concern
- For detection device makers → finding the best match between detection technical possibilities and birds flight behaviour
- For turbine makers → incentive to reduce shutdown duration

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Perspectives:

- More shutdown tests at high wind speed with more machines → robustness of shutdown durations estimates
- List of species available can be updated for other continents (depending on availability of new data of flight speed)

Researchers who shared unpublished bird GPS tracking data

Anny Anselin (Research Institute for Nature and Forest)

Patrik Byholm (University of Helsinki)

Nelleke Buitendijk (Netherlands Institute of Ecology)

Jocelyn Champagnon (Tour du Valat, France)

Mindaugas Dagys (Nature Research Centre)

Olivier Duriez (University of Montpellier)

Charlotte Francesiaz (OFB)

Guilad Friedemann (University of Tel Aviv)

Scott Jennings (Audubon Canyon Ranch)

Erick Kobierzycki (LPO)

Petras Kurlavicius (Vytautas Magnus university)

Simon Lee

Santiago Mañosa Rifé (University of Barcelona)

Alexandre Million (IMBE)

Flavio Monti (University of Montpellier)

Ran Nathan (University of Jerusalem)

Bart Nolet (Netherlands Institute of Ecology)

Rascha Nuijten (Netherlands Institute of Ecology)

Philippe Pillard (LPO)

Cécile Ponchon (CEN PACA)

Alexandre Roulin (University of Lausanne)

Carlos D. Santos (Max Planck Institute)

Kim Schalcher (University of Lausanne)

Tonio Schaub (IMBE, Aix-Marseille University, University of Groningen, Dutch Montagu's Harrier Foundation)

Almut Schlaich (Dutch Montagu's Harrier Foundation, Groningen Institute)

Aurélie de Seynes (LPO)

Geert Spanoghe (Research Institute for Nature and Forest)

Orr Spiegel (University of Jerusalem)

Martin Wikelski (Max Planck Institute)

Ramunas Žydelis (Nature Research Centre)

Researchers who helped at various stages of the project

- Bruno Bruderer
- Joao Guilherme-Lopes
- Steffen Hahn

